# GEOMETRIC STRUCTURES WITH A DENSE INDEPENDENT SUBSET 

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#### Abstract

We generalize the work of [13] on expansions of o-minimal structures with dense independent subsets, to the setting of geometric structures We introduce the notion of an $H$-structure of a geometric theory $T$, show that $H$-structures exist and are elementarily equivalent, and establish some basic properties of the resulting complete theory $T^{i n d}$, including quantifier elimination down to " $H$-bounded" formulas, and a description of definable sets and algebraic closure. We show that if $T$ is strongly minimal, supersimple of SUrank 1 , or superrosy of thorn rank 1 , then $T^{\text {ind }}$ is $\omega$-stable, supersimple, and superrosy, respectively, and its $\mathrm{U}-/ \mathrm{SU}-/$ thorn rank is either 1 (if $T$ is trivial) or $\omega$ (if $T$ is non-trivial). In the supersimple SU-rank 1 case, we obtain a description of forking and canonical bases in $T^{i n d}$. We also show that if $T$ is (strongly) dependent, then so is $T^{i n d}$, and if $T$ is non-trivial of finite dp-rank, then $T^{\text {ind }}$ has dp-rank greater than $n$ for every $n<\omega$, but bounded by $\omega$. In the stable case, we also partially solve the question of whether any group definable in $T^{i n d}$ comes from a group definable in $T$.


## 1. Introduction

We say a theory $T$ is geometric if for any model $M \models T$ the algebraic closure satisfies the exchange property and $T$ eliminates the quantifier $\exists^{\infty}$ (see [20, Def. $2.1]$, [17]). There are many examples of geometric theories, among them dense ominimal theories, strongly minimal theories, SU-rank 1 theories, the p-adics in a single sort, etc.

Expansions of geometric theories with a unary predicate have been studied extensively. There are expansions where the underlying model $M$ is an algebraically closed or a real closed field and the predicate is interpreted as a multiplicative subgroup, for example to study groups with the Mann property [15]. This expansion created a nice framework for studying groups satisfying the Mordell-Lang property inside a fixed field. In the same way, the work on rational points of eliptic curves from [18] gives connections with number theory.

Another such expansion corresponds to lovely pairs [6,3]. Let $\mathcal{L}$ be the language of $T$, let $M \models T$ and let $H$ be a new unary predicate that does not belong to $\mathcal{L}$. For $M \models T$, we say that $(M, H(M))$ is a lovely pair if $H(M)$ is an elementary substructure of $M$, the predicate satisfies the density property (for any infinite $\mathcal{L}$ formula $\varphi(x, \vec{b})$ with parameters in $M, \varphi(H(M)) \neq \emptyset)$ and $M$ satisfies the extension property over $H(M)$ (for any infinite $\mathcal{L}$-formula $\varphi(x)$ with parameters in $M,(\varphi(M) \backslash$ $\operatorname{acl}(H(M) \vec{b})) \neq \emptyset)$. Lovely pairs are a tool for understanding the properties of the

[^0]underlying geometry such as linearity. The structure imposed on the predicate, i.e. being an elementary substructure, a subgroup, allows one to use the expansion to get an insight into different properties of $T$ or structures living inside a model of $T$.

Generic (random) predicate expansions have also been studied extensively, e.g. by Chatzidakis and Pillay in [11]. In the strongly minimal case they provide "natural" examples of unstable supersimple structures of SU-rank 1. Baldwin and Benedikt [1] have also considered expansions by indiscernible sequences.

In this paper we will explore an expansion, introduced in the o-minimal case in [13], which in some sense is dual to the lovely pairs expansion. We will assume that $H(M)$ is a collection of algebraically independent elements satisfying the density and extension properties. The construction is a dual in the sense that instead of assuming the predicate to be an elementary substructure, we assume it is a collection of "geometrically unrelated" (algebraically independent) elements. We call such an expansion $(M, H)$ an $H$-structure, and we write $T^{\text {ind }}$ for its theory.

Examples of $T^{\text {ind }}$ include the theory of a vector space with a distinguished basis and the theory of a real closed field with a distinguished dense transcendence basis.

Some properties of this expansion are very similar to those of lovely pairs. For example, we show in Section 2 that saturated models of $T^{\text {ind }}$ are again $H$-structures. We show in Section 3 that the definable subsets of $H(M)$ are just intersections of $\mathcal{L}$ definable formulas with $H$. We also show that the definable subsets of $(M, H(M))$ come as boolean combinations of $\mathcal{L}$-formulas enlarged by existential quantifiers over $H$. While the question of elimination of $\exists^{\infty}$ in $T^{i n d}$ remains open, we show that it holds for formulas where parameters are assumed to be in $H(M)$. As in the pairs setting, one of the central notions in the study of $H$-structures is that of the large and small set. What is different from the case of pairs is that in $H$-structures we also have the notion of " $H$-basis" of a tuple (over $\emptyset$ or another set). On one hand, this notion allows one to "coordinatize" the structure by elements of $H$ and elements orthogonal to $H$, while on the other hand it generates a variety of new definable functions from definable sets in $(M, H)$ to $H(M)$.

In Section 4 we explore some additional topics related to $H$-structures motivated by the analogies with the pair expansions. In subsection 4.1 we compare $H$-structures with lovely pairs and show how to build a lovely pair out of an $H$ structure. Subsection 4.2 iterates the construction of $H$-structures to tuples, following similar ideas of Poizat on beautiful pairs [24] and of Fornasiero for closure relations [16]. In subsection 4.3, we show elimination of $\exists y \in H$ for the expansion of $H(M)$ by externally definable sets.

In Section 5 we show that if $T$ is strongly minimal (respectively $T$ has SU-rank 1, thorn-rank 1), then $M R\left(T^{\text {ind }}\right) \leq \omega$ (respectively $\operatorname{SU}-r a n k\left(T^{\text {ind }}\right) \leq \omega$, thorn$\left.\operatorname{rank}\left(T^{i n d}\right) \leq \omega\right)$. We obtain a description of forking and canonical bases in $T^{\text {ind }}$ when $T$ is supersimple of SU-rank 1 . We also observe a (somewhat surprising) fact that that one-basedness is not preserved when passing to $T^{i n d}$.

In the lovely pair case, the rank of the expansion captured the geometric complexity of the base theory (along the lines of the trivial/linear/non-linear trichotomy). Similar, but much less refined, connection takes place in the case of $H$-structures: non-triviality of the base theory guarantees that the expansion will have the maximal rank $\omega$.

Finally in this section we show that if $T$ is (strongly) dependent, $T^{i n d}$ is also (strongly) dependent. As before there is a connection between the triviality of $T$
and the dp-rank. When $T$ is trivial and $T$ has dp-rank $n$, then so does $T^{\text {ind }}$, if $T$ is not trivial and $T$ has dp-rank $n$, then $T^{i n d}$ has dp-rank greater than or equal to $k$ for all $k$.

In Section 6 we study groups definable in a $H$-structure $(M, H)$. Since the geometry on $H$ is trivial, we expected that adding $H$ should not introduce new definable groups. We managed to show this claim only partially. When $T$ is stable we show that every connected group definable in $(M, H)$ is definably isomorphic to a group interpretable in $M$.

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## 2. $H$-Structures: DEfinition and first properties

Let $T$ be a complete geometric theory in a language $\mathcal{L}$. Thus, in any model $M \models T$, the algebraic closure satisfies the Exchange Property and $T$ eliminates the quantifier $\exists^{\infty}$. Let $H$ be a new unary predicate and let $\mathcal{L}_{H}=\mathcal{L} \cup\{H\}$. Let $T^{\prime}$ be the $\mathcal{L}_{H}$-theory of all structures $(M, H)$, where $M \models T$ and $H(M)$ is an $\mathcal{L}$-algebraically independent subset of $M$. Note that saying that $H(M)$ is independent is a first order property, it is simply the conjunctions of formulas of the form $\neg \varphi\left(x_{1}, \ldots, x_{n}\right)$, where $\operatorname{dim}\left(\varphi\left(x_{1}, \ldots, x_{n}\right)\right)<n$.
Notation 2.1. Let $(M, H(M)) \models T^{\prime}$ and let $A \subset M$. We write $H(A)$ for $H(M) \cap$ A.

Notation 2.2. Throughout this paper independence (and the corresponding notation $\downarrow)$ means acl-independence, where acl stands for the algebraic closure in the sense of $\mathcal{L}$. We write $\operatorname{tp}(\vec{a})$ for the $\mathcal{L}$-type of a and dcl, acl for the definable closure and the algebraic closure in the language $\mathcal{L}$. Similarly we write $\mathrm{dcl}_{H}, \operatorname{acl}_{H}, \operatorname{tp}_{H}$ for the definable closure, the algebraic closure and the type in the language $\mathcal{L}_{H}$. For $A \subset B$ sets and $q \in S_{n}(B)$, we say that $q$ is free over $A$ or that $q$ is a free extension of $q \upharpoonright_{A}$ if for any (all) $\vec{c} \models q, \vec{c}$ is independent from $B$ over $A$.
Definition 2.3. We say that $(M, H(M))$ is an $H$-structure if
(1) $(M, H(M)) \models T^{\prime}$
(2) (Density/coheir property) If $A \subset M$ is finite dimensional and $q \in S_{1}(A)$ is non-algebraic, there is $a \in H(M)$ such that $a \models q$.
(3) (Extension property) If $A \subset M$ is finite dimensional and $q \in S_{1}(A)$ is non-algebraic, there is $a \in M, a \models q$ and $a \notin \operatorname{acl}(A \cup H(M))$.
Lemma 2.4. Let $(M, H(M)) \models T^{\prime}$. Then $(M, H(M))$ is an $H$-structure if and only if:
(2') (Generalized density/coheir property) If $A \subset M$ is finite dimensional and $q \in S_{n}(A)$ has dimension $n$, then there is $\vec{a} \in H(M)^{n}$ such that $\vec{a} \models q$.
(3') (Generalized extension property) If $A \subset M$ is finite dimensional and $q \in$ $S_{n}(A)$, then there is $\vec{a} \in M^{n}$ realizing $q$ such that $\operatorname{tp}(\vec{a} / A \cup H(M))$ is free over $A$.
Proof. We prove (2') and leave (3') to the reader. Let $\vec{b} \models q$, we may write $\vec{b}=$ $\left(b_{1}, \ldots, b_{n}\right)$. Since $(M, H(M))$ is an $H$-structure, applying $n$ times the density property we can find $a_{1}, \ldots, a_{n} \in H(M)$ such that

$$
\operatorname{tp}\left(a_{1}, \ldots, a_{n} / \operatorname{acl}(A)\right)=\operatorname{tp}\left(b_{1}, \ldots, b_{n} / \operatorname{acl}(A)\right)
$$

Note that if $(M, H(M))$ is an $H$-structure, the extension property implies that $M$ is $\aleph_{0}$-saturated.
Remark 2.5. Assume now that $T$ is a geometric theory expanding DLO and that $(M, H(M))$ is an $H$-structure. Let $a, b \in M$ be such that $a<b$; then the partial type $a<x<b$ is non-algebraic and by the density property it is realized in $H(M)$. Thus, the density property implies that $H(M)$ is dense in $M$. The density property that we use in this paper can be traced back to Macintyre [21], it also appears under the name of coheir property in [2].

Definition 2.6. Let $A$ be a subset of an $H$-structure $(M, H(M))$. We say that $A$ is $H$-independent if $A$ is independent from $H(M)$ over $H(A)$.

Lemma 2.7. Any model $M$ of $T$ with a distinguished independent subset $H(M)$ can be embedded in a model of $T^{\prime}$ in an $H$-independent way.
Proof. Given any model $M$ with a distinguished independent subset $H(M)$, we can always find an elementary extension $N$ of $M$ and a set $H(N)$ extending $H(M)$ such that for every non-algebraic 1-type $p(x, \operatorname{acl}(\vec{m}))$, where $\vec{m} \in M$, there are $d \in N$ and $b \in H(N)$ such that both $b$ and $d$ realize $p(x, \operatorname{acl}(\vec{m}))$ and $d \notin \operatorname{acl}(M, H(N))$. Now apply a chain argument.

In particular, for a geometric theory $T, H$-structures exist.
Lemma 2.8. Let $(M, H)$ and $(N, H)$ be sufficiently saturated models of $T^{\prime}, \vec{a} \in M$ and $\vec{a}^{\prime} \in N H$-independent tuples such that $\operatorname{tp}(\vec{a}, H(\vec{a}))=\operatorname{tp}\left(\vec{a}^{\prime}, H\left(\vec{a}^{\prime}\right)\right)$. Then $t p_{H}(\vec{a})=\operatorname{tp}_{H}\left(\vec{a}^{\prime}\right)$.
Proof. Let $\vec{a}=\vec{a}_{0} \vec{a}_{1} \vec{h}$, where $\vec{a}_{0}$ is independent over $H, \vec{h} \in H$ and $\vec{a}_{1} \in \operatorname{acl}\left(\vec{a}_{0} \vec{h}\right)$. Similarly write $\vec{a}^{\prime}=\vec{a}_{0}^{\prime} \vec{a}_{1}^{\prime} \vec{h}^{\prime}$.

To prove the Lemma we show that the partial isomorphism that sends $\vec{a}$ to $\vec{a}^{\prime}$ can be extended, so it suffices to show that for any $b \in M$ there are $\vec{h}_{1} \in H(M)$, $\vec{h}_{1}^{\prime} \in H(N)$ and $b^{\prime} \in N$ such that $\vec{a} \vec{h}_{1} b$ and $\vec{a}^{\prime} \vec{h}_{1}^{\prime} b^{\prime}$ are each $H$-independent, $\operatorname{tp}\left(\vec{a}_{0} \vec{a}_{1} \vec{h} \vec{h}_{1} b\right)=\operatorname{tp}\left(\vec{a}_{0}^{\prime} \vec{a}_{1}^{\prime} \vec{h}^{\prime} \vec{h}_{1}^{\prime} b^{\prime}\right)$, and $b \in H(M)$ iff $b^{\prime} \in H(N)$.

Case 1: $b \in \operatorname{acl}(\vec{a})$. By $H$-independence, either $b \in \vec{h}$ or $b \notin H(M)$. Let $b^{\prime} \in \operatorname{acl}\left(\vec{a}^{\prime}\right)$ be such that $\operatorname{tp}\left(b^{\prime} \vec{a}^{\prime}\right)=\operatorname{tp}(b \vec{a})$. Clearly, $b \in H(M)$ iff $b^{\prime} \in H(N)$. Here we can take $\vec{h}_{1}$ and $\vec{h}_{1}^{\prime}$ to be empty.

Case 2: $b \in H$ and is non algebraic over $\vec{a}$. By the density property, we can find $b^{\prime} \in H(N)$ such that $\operatorname{tp}\left(b^{\prime} \vec{a}^{\prime}\right)=\operatorname{tp}(b \vec{a})$. Here again we can take $\vec{h}_{1}$ and $\vec{h}_{1}^{\prime}$ to be empty.

Case 3: $b \in \operatorname{acl}(H \vec{a})$. Add a tuple $\vec{h}_{1} \in H$ such that $\vec{a} b \vec{h}_{1}$ is $H$-independent, and use Cases 1 and/or 2.

Case 4: $b \notin \operatorname{acl}(H \vec{a})$. By the extension property, there is $b^{\prime} \in N$ such that $b^{\prime} \notin \operatorname{acl}\left(H \vec{a}^{\prime}\right)$ and $\operatorname{tp}\left(b^{\prime} \vec{a}^{\prime}\right)=\operatorname{tp}(b \vec{a})$. The tuples stay $H$-independent, so again we can take $\vec{h}_{1}$ and $\vec{h}_{1}^{\prime}$ to be empty.

The previous result has the following consequence:
Corollary 2.9. All $H$-structures are elementarily equivalent.
We write $T^{\text {ind }}$ for the common complete theory of all $H$-structures of models of $T$.

To axiomatize $T^{\text {ind }}$ we follow the ideas of [27, Prop 2.15]. Here we use for the first time the fact that $T$ eliminates $\exists^{\infty}$. Recall that whenever $T$ eliminates $\exists^{\infty}$ the expression the formula $\varphi(x, \vec{b})$ is nonalgebraic is first order.
Proposition 2.10. The theory $T^{\text {dim }}$ is axiomatized by:
(1) $T^{\prime}$.
(2) For all $\mathcal{L}$-formulas $\varphi(x, \vec{y})$ $\forall \vec{y}(\varphi(x, \vec{y})$ nonalgebraic $\Longrightarrow \exists x(\varphi(x, \vec{y}) \wedge x \in H))$.
(3) For all $\mathcal{L}$-formulas $\varphi(x, \vec{y}), m \in \omega$, and all $\mathcal{L}$-formulas $\psi\left(x, z_{1}, \ldots, z_{m}, \vec{y}\right)$ such that for some $n \in \omega \forall \vec{z} \forall \vec{y} \exists \leq n x \psi(x, \vec{z}, \vec{y})$ (so $\psi(x, \vec{y}, \vec{z})$ is always algebraic in $x$ ) $\forall \vec{y}(\varphi(x, \vec{y})$ nonalgebraic $\Longrightarrow \exists x(\varphi(x, \vec{y}) \wedge$ $\left.\forall w_{1} \ldots \forall w_{m} \in H \neg \psi\left(x, w_{1}, \ldots, w_{m}, \vec{y}\right)\right)$

Furthermore, if $(M, H(M)) \models T^{\text {ind }}$ is $|T|^{+}$-saturated, then $(M, H(M))$ is an H -structure.
The second scheme of axioms corresponds to the density property and the third scheme to the extension property. The first axiom says that $H$ is a collection of independent elements. The proof is the same on as the one in [3, Thm 2.10].
Example 2.11. Let $T$ be the theory of infinite dimensional vector spaces over $a$ fixed finite field, say $F_{2}$. Note that $T$ is strongly minimal so $T$ is geometric. Let $V \models T$ be countable and let $H=\left\{v_{j}: j \in \omega\right\}$ be its basis. Then $(V, H) \models T^{\text {ind }}$ but it is NOT an $H$-structure since it does not satisfy the extension property.
Example 2.12. Let $T=T h(\mathbb{R},+, \times, 0,1,<), T$ is o-minimal extending $D L O$ so $T$ is geometric. Let $H=\left\{e_{i}: i \in I\right\}$ be a dense trascendence basis, then $(\mathbb{R}, H) \models$ $T^{\text {ind }}$. Note that $(\mathbb{R}, H)$ is not an $H$-structure, since it does not satisfy the extension property.

## 3. Definable sets in $H$-structures

Fix $T$ a geometric theory and let $(M, H(M)) \models T^{\text {ind }}$. Our next goal is to obtain a description of definable subsets of $M$ and $H(M)$ in the language $\mathcal{L}_{H}$. We will also address the question of the elimination of $\exists^{\infty}$ in $T^{\text {ind }}$.
Notation 3.1. Let $(M, H(M))$ be an $H$-structures. Let $\vec{a}$ be a tuple in $M$. We denote by $\operatorname{etp}_{H}(\vec{a})$ the collection of formulas of the form $\exists x_{1} \in H \ldots \exists x_{m} \in H \varphi(\vec{x}, \vec{y})$, where $\varphi(\vec{x}, \vec{y})$ is an $\mathcal{L}$ formula such that there exists $\vec{h} \in H$ with $M \models \varphi(\vec{h}, \vec{a})$.
Lemma 3.2. Let $(M, H(M)),(N, H(N))$ be $H$-structures. Let $\vec{a}, \vec{b}$ be tuples of the same arity from $M, N$ respectively. Then the following are equivalent:
(1) $\operatorname{etp}_{H}(\vec{a})=\operatorname{etp}_{H}(\vec{b})$.
(2) $\vec{a}, \vec{b}$ have the same $\mathcal{L}_{H}$-type.

Proof. Clearly (2) implies (1). Assume (1), then $\operatorname{tp}(\vec{a})=\operatorname{tp}(\vec{b})$.
Claim $\operatorname{dim}(\vec{b} / H)=\operatorname{dim}(\vec{a} / H)$.

Let $\vec{h}=\left(h_{1}, \ldots, h_{l}\right) \in H(M)$ be such $k:=\operatorname{dim}(\vec{a} / \vec{h})=\operatorname{dim}(\vec{a} / H(M))$. We may assume that $\vec{a}^{1}=\left(a_{1}, \ldots, a_{k}\right)$ are independent over $H$ and $\vec{a}^{2}=\left(a_{k+1}, \ldots, a_{n}\right) \in$ $\operatorname{acl}\left(a_{1}, \ldots, a_{k}, h_{1}, \ldots, h_{l}\right)$. Choose $\psi(\vec{x}, \vec{y}, \vec{z})$ such that for any $\vec{b} \in M, \vec{c} \in M$ $\psi(\vec{b}, \vec{c}, \vec{z})$ is always algebraic in $\vec{z}$ and $M \models \psi\left(\vec{h}, \vec{a}^{1}, \vec{a}^{2}\right)$. Since $\operatorname{etp}_{H}(\vec{a})=\operatorname{etp}_{H}(\vec{b})$ we get that $\operatorname{dim}(\vec{b} / H) \leq k$. A similar argument shows that $\operatorname{dim}(\vec{a} / H(M)) \leq$ $\operatorname{dim}(\vec{b} / H(N))$.

Claim $\operatorname{tp}_{H}(\vec{b})=\operatorname{tp}_{H}(\vec{a})$.
As before, let $\vec{h}=\left(h_{1}, \ldots, h_{l}\right) \in H(M)$ be such that $k:=\operatorname{dim}(\vec{a} / \vec{h})=\operatorname{dim}(\vec{a} / H(M))$. Then $\vec{a} \vec{h}$ is $H$-independent. Since $N$ is saturated as an $\mathcal{L}$-structure there are $\vec{h}^{\prime}=\left(h_{1}^{\prime}, \ldots, h_{l}^{\prime}\right) \in H$ such that $\operatorname{tp}(\vec{a}, \vec{h})=\operatorname{tp}\left(\vec{b}, \vec{h}^{\prime}\right)$. By the claim above $\vec{b} \vec{h}^{\prime}$ is $H$-independent, so the result follows from Lemma 2.8.
Corollary 3.3. Let $(M, H(M))$ be a sufficiently saturated $H$-structure, assume that $T=T h(M)$ is trivial and that $\mathrm{dcl}=\operatorname{acl}$ in $T$. Then every $\mathcal{L}_{H}$ formula $\varphi(\vec{x})$ in $(M, H(M))$ is equivalent to a boolean combination of $\mathcal{L}$ formulas and formulas of the form $H(f(\vec{x}))$, where $f$ is an $\mathcal{L}$-definable function.

Proof. It suffices to check that types of tuples in $(M, H(M))$ are isolated by the the $\mathcal{L}$-formulas that they satisfy and the values of expressions of the form $H(f(\vec{x}))$, where $f$ is an $\mathcal{L}$-definable function..

Let $\vec{a}, \vec{b}$ be tuples of the same arity from $M$ and assume that they satisfy the same $\mathcal{L}$-type and that for every $\mathcal{L}$-definable function $f(\vec{x})$ we have that $H(f(\vec{a}))$ holds if and only if $H(f(\vec{b}))$ holds. We will prove that $\operatorname{tp}_{H}(\vec{a})=\operatorname{tp}_{H}(\vec{b})$.

Claim $\operatorname{dim}(\vec{b} / H)=\operatorname{dim}(\vec{a} / H)$.
Let $\vec{h}=\left(h_{1}, \ldots, h_{l}\right) \in H(M)$ be such $k:=\operatorname{dim}(\vec{a} / \vec{h})=\operatorname{dim}(\vec{a} / H(M))$ and assume that $\vec{h}$ is a minimal such tuple. Then since $T$ is trivial, for each $i \leq k$ we have that $h_{i}=f_{i}\left(a_{j_{i}}\right)$ for some $j_{i}$ and some $\mathcal{L}$-definable function $f_{i}$. Let $h_{i}^{\prime}=f_{i}\left(b_{j_{i}}\right)$ and let $\vec{h}^{\prime}=\left(h_{1}^{\prime}, \ldots, h_{l}^{\prime}\right)$. Then $H\left(h_{i}^{\prime}\right)$ holds for each $i \leq l$ and $\operatorname{dim}(\vec{b} / H) \leq l=$ $\operatorname{dim}(\vec{a} / H)$. The other inequality follows in the same way.

Note that for $\vec{h}$ and $\vec{h}^{\prime}$ defined as above, we have that $\vec{a} \vec{h}$ and $\vec{b} \vec{h}^{\prime}$ are $H$ independent and thus by Lemma 2.8 we have that $\operatorname{tp}(\vec{a})=\operatorname{tp}(\vec{b})$ as desired.

Now we are interested in the $\mathcal{L}_{H}$-definable subsets of $H(M)$. This material is very similar to the results presented in [14, Theorem 2].

Lemma 3.4. Let $\left(M_{0}, H\left(M_{0}\right)\right) \preceq\left(M_{1}, H\left(M_{1}\right)\right)$ and assume that $\left(M_{1}, H\left(M_{1}\right)\right)$ is $\left|M_{0}\right|$-saturated. Then $M_{0}$ (seen as a subset of $M_{1}$ ) is a $H$-independent set.

Proof. Assume not. Then there are $a_{1}, \ldots, a_{n} \in M_{0} \backslash H\left(M_{0}\right)$ such that $a_{n} \in$ $\operatorname{acl}\left(a_{1}, \ldots, a_{n-1}, H\left(M_{1}\right)\right)$ and $a_{n} \notin \operatorname{acl}\left(a_{1}, \ldots, a_{n-1}, H\left(M_{0}\right)\right)$. Let $\varphi(x, \vec{y}, \vec{z})$ be a formula and $\vec{b} \in H\left(M_{1}\right)_{\vec{z}}$ be a tuple such that

$$
\varphi\left(a_{n}, a_{1}, \ldots, a_{n-1}, \vec{b}\right) \wedge \exists^{\leq n} x \varphi\left(x, a_{1}, \ldots, a_{n-1}, \vec{b}\right)
$$

holds. Since $\left(M_{0}, H\left(M_{0}\right)\right) \preceq\left(M_{1}, H\left(M_{1}\right)\right)$ there is $\vec{b}^{\prime} \in H\left(M_{0}\right)_{\vec{y}}$ such that

$$
\varphi\left(a_{n}, a_{1}, \ldots, a_{n-1}, \vec{b}^{\prime}\right) \wedge \exists \leq n x \varphi\left(x, a_{1}, \ldots, a_{n-1}, \vec{b}^{\prime}\right)
$$

holds, so $a_{n} \in \operatorname{acl}\left(a_{1}, \ldots, a_{n-1}, H\left(M_{0}\right)\right)$, a contradiction.
Proposition 3.5. Let $(M, H(M))$ be an $H$-structure and let $Y \subset H(M)^{n}$ be $\mathcal{L}_{H^{-}}$ definable. Then there is $X \subset M^{n} \mathcal{L}$-definable such that $Y=X \cap H(M)^{n}$.

Proof. Let $\left(M_{1}, H\left(M_{1}\right)\right) \succeq(M, H(M))$ be $\kappa$-saturated where $\kappa>|M|+|L|$ and let $\vec{a}, \vec{b} \in H\left(M_{1}\right)^{n}$ be such that $\operatorname{tp}(\vec{a} / M)=\operatorname{tp}(\vec{b} / M)$. We will prove that $\operatorname{tp}_{H}(\vec{a} / M)=$ $\operatorname{tp}_{H}(\vec{b} / M)$ and the result will follow by compactness. Since $\vec{a}, \vec{b} \in H\left(M_{1}\right)^{n}$, we get by Lemma 3.4 that $M \vec{a}, M \vec{b}$ are $H$-independent sets and thus by Lemma 2.8 we get $\operatorname{tp}_{H}(\vec{a} / M)=\operatorname{tp}_{H}(\vec{b} / M)$.

Remark 3.6. A small warning is due here. In the previous proof, we may need extra parameters in the small model to define an $\mathcal{L}$-formula equivalent to the original $\mathcal{L}_{H}$-formula.

Definition 3.7. Let $(M, H) \models T^{i n d}$ be saturated. We say that an $\mathcal{L}_{H}$ formula $\psi(x, \vec{c})$ defines a large subset of $M$ is there is $b \models \psi(x, \vec{c})$ such that $b \notin \operatorname{scl}(\vec{c})$. This is equivalent as requiring that there are infinitely many realizations of $\psi(x, \vec{c})$ that are algebraically independent over $H(M) \vec{c}$.
Definition 3.8. Let $(M, H) \models T^{\text {ind }}$ be $\kappa$-saturated and let $A \subset M$ be smaller than $\kappa$. Let $\vec{b} \in M$ be a tuple. We say that $\vec{b}$ is in the small closure of $A$ if $\vec{b} \in \operatorname{acl}(A H(M))$ and write $\vec{b} \in \operatorname{scl}(A)$. Let $X \subset M^{n}$ be $A$-definable. We say that $X$ is small if $X \subset \operatorname{scl}(A)$.

Since $T$ is geometric, scl satisfies the exchange property and thus it is a closure operator.

Next, we introduce the notion of the $H$-basis, which first appeared in [13] in the o-minimal context.
Proposition 3.9. Let $(M, H(M))$ be an $H$-structure. Let $\vec{a}=\left(a_{1}, \ldots, a_{n}\right) \in M$. Then there is a unique smallest tuple $\vec{h} \in H(M)$ such that $\vec{a} \downarrow_{\vec{h}} H$.
Proof. Clearly there is a tuple $\vec{h} \in H$ such that $\vec{a} \downarrow_{\vec{h}} H$. Choose such a tuple so that $|\vec{h}|$ (the length of the tuple) is minimal. We will now show such a tuple $\vec{h}$ is unique (up to permutation).

We can write $\vec{a}=\left(\vec{a}_{1}, \vec{a}_{2}\right)$ so that $\vec{a}_{1}$ is independent over $H(M)$ and $\vec{a}_{2} \in \operatorname{scl}\left(\vec{a}_{1}\right)$. If $\vec{a}_{2}=\emptyset$, then $\vec{h}=\emptyset$ and the result follows. So we may assume that $\vec{a}_{2} \neq \emptyset$.

Then $\vec{a}_{2} \in \operatorname{acl}\left(\vec{a}_{1}, \vec{h}\right)$. Let $\vec{h}^{\prime}$ be another such tuple. Let $\vec{h}_{1}$ be the list of common elements in both $\vec{h}$ and $\vec{h}^{\prime}$, so we can write $\vec{h}=\left(\vec{h}_{1}, \vec{h}_{2}\right)$ and $\vec{h}^{\prime}=\left(\vec{h}_{1}, \vec{h}_{2}^{\prime}\right)$.

Claim $\vec{h}_{2}=\vec{h}_{2}^{\prime}=\emptyset$.
Assume otherwise. Since $\vec{a}_{2} \in \operatorname{acl}\left(\vec{a}_{1}, \vec{h}_{1}, \vec{h}_{2}\right) \backslash \operatorname{acl}\left(\vec{a}_{1}, \vec{h}_{1}\right)$ and $\vec{a}_{2} \in \operatorname{acl}\left(\vec{a}_{1}, \vec{h}_{1}, \vec{h}_{2}^{\prime}\right) \backslash$ $\operatorname{acl}\left(\vec{a}_{1}, \vec{h}_{1}\right)$ then by the exchange property $\operatorname{dim}\left(\vec{h}_{2}^{\prime} / \vec{a}_{1} \vec{h}_{1} \vec{h}_{2}\right)<\operatorname{dim}\left(\vec{h}_{2}^{\prime} / \vec{a}_{1} \vec{h}_{1}\right)$. Since $\vec{a}_{1}$ is independent over $H$ we get that $\operatorname{dim}\left(\vec{h}_{2}^{\prime} / \vec{h}_{1} \vec{h}_{2}\right)<\operatorname{dim}\left(\vec{h}_{2}^{\prime} / \vec{h}_{1}\right)$ and thus since $H$ is independent, $\vec{h}_{2}$ has a common element with $\vec{h}_{2}^{\prime}$, a contradiction.

Remark 3.10. Let $(M, H(M))$ be an $H$-structure. Let $\vec{a}=\left(a_{1}, \ldots, a_{n}\right) \in M$ and let $C \subset M$ be such that $C=\operatorname{acl}(C)$ and $C$ is $H$-independent. As before, there is a unique smallest tuple $\vec{h} \in H(M)$ such that $\vec{a} \downarrow_{\vec{h} C} H$.
Definition 3.11. Let $(M, H(M))$ be an $H$-structure. Let $\vec{a}=\left(a_{1}, \ldots, a_{n}\right) \in M$. Let $\vec{h} \in H(M)$ be the smallest tuple such that $\vec{a} \downarrow_{\vec{h}} H$. We call $\vec{h}$ the $H$-basis of $\vec{a}$ and we denote it as $H B(\vec{a})$. Given $C \subset M$ such that $C=\operatorname{acl}(C)$ and $C$ is $H$-independent, let $\vec{h} \in H(M)$ the smallest tuple such that $\vec{a} \downarrow_{C \vec{h}} H$. We call $\vec{h}$ the $H$-basis of $\vec{a}$ over $C$ and we denote it as $H B(\vec{a} / C)$. Note that $H$-basis is unique
up to permutation, therefore we will view the $H$-basis $\vec{h}=\left(h_{1}, \ldots, h_{k}\right)$ either as a finite set $\left\{h_{1}, \ldots, h_{k}\right\}$ or as the imaginary representing this finite set. If we view it as a tuple, we will explicitly say so.

We will first apply the $H$-basis to characterize definable sets in terms of $\mathcal{L}$ definable sets.

Proposition 3.12. Let $(M, H(M))$ be an $H$-structure and let $Y \subset M$ be $\mathcal{L}_{H^{-}}$ definable. Then there is $X \subset M \mathcal{L}$-definable such that $Y \triangle X$ is small, where $\triangle$ stands for a boolean connective for the symmetric difference.

Proof. If $Y$ is small or cosmall, the result is clear, so we may assume that both $Y$ and $M \backslash Y$ are large. Assume that $Y$ is definable over $\vec{a}$ and that $\vec{a}=\vec{a} H B(\vec{a})$. Let $b \in Y$ be such that $b \notin \operatorname{scl}(\vec{a})$ and let $c \in M \backslash Y$ be such that $c \notin \operatorname{scl}(\vec{a})$. Then $b \vec{a}$, $c \vec{a}$ are $H$-independent and thus there is $X_{b c}$ an $\mathcal{L}$-definable set such that $b \in X_{b c}$ and $c \notin X_{b c}$. By compactness, we may first assume that $X_{b c}$ only depends on $\operatorname{tp}(b / \vec{a})$ and applying compactness again we may assume that $X_{b c}$ does no depend on $\operatorname{tp}(b / \vec{a})$ and we will call it simply $X$. Thus for $b^{\prime} \in Y$ and $c^{\prime} \in M \backslash Y$ not in the small closure of $\vec{a}$, we have $b^{\prime} \in X$ and $c^{\prime} \in M \backslash X$. This shows that $Y \triangle X$ is small.

Our next goal is to characterize the algebraic closure in $H$-structures. The key tool is the following result:

Lemma 3.13. Let $T$ be a geometric theory, $M \models T$, $(M, H(M))$ an $H$-structure, and let $A \subset M$ be acl-closed and $H$-independent. Then $A$ is acl $_{H}$-closed.

Proof. Suppose $a \in M, a \notin A$. If $a \notin \operatorname{scl}(A)$, then $A \cup\{a\}$ is $H$-independent, and using the extension property, we can find $a_{i}, i \in \omega$, acl-independent over $A \cup H(M)$, realizing $\operatorname{tp}(a / A)$. By Lemma 2.8, each $a_{i}$ realizes $\operatorname{tp}_{H}(a / A)$, and thus $a \notin \operatorname{acl}_{H}(A)$.

If $a \in \operatorname{scl}(A)$, take a minimal tuple $\vec{b} \in H(M)$ such that $a \in \operatorname{acl}(A \vec{b})$. Using the coheir property of $H$-structures, we can find $\vec{b}_{i} \in H(M), i \in \omega$, such that $\vec{b}_{i}$ are acl-independent over $A$ and realize $\operatorname{tp}(\vec{b} / A)$. Take $a_{i} \in \operatorname{acl}\left(A \vec{b}_{i}\right)$ such that $\operatorname{tp}\left(a_{i} \vec{b}_{i} / A\right)=\operatorname{tp}(a \vec{b} / A)$. Then $\left\{a_{i}: i \in \omega\right\}$ are acl-independent over $A$. On the other hand, for any $i \in \omega, A \vec{b}_{i} a_{i}$ is a $H$-independent set and thus by Lemma 2.8 $\operatorname{tp}_{H}\left(a_{i} \vec{b}_{i} / A\right)=\operatorname{tp}_{H}(a \vec{b} / A)$ and in particular $\operatorname{tp}_{H}\left(a_{i} / A\right)=\operatorname{tp}_{H}(a / A)$.

Corollary 3.14. Let $T$ be a geometric theory, $M \models T,(M, H(M))$ an $H$-structure, and let $A \subset M$. Then $\operatorname{acl}_{H}(A)=\operatorname{acl}(A, H B(A))$.

Proof. By Proposition 3.9, it is clear that $H B(A) \in \operatorname{acl}(A), \operatorname{socl}_{H}(A) \supset \operatorname{acl}(A, H B(A))$. On the other hand, $A, H B(A)$ is $H$-closed, so by the previous Proposition, $\operatorname{acl}(A, H B(A))=$ $\operatorname{acl}_{H}(A, H B(A))$ and thus $\operatorname{acl}_{H}(A) \subset \operatorname{acl}(A, H B(A))$

It is interesting to check which properties of $T$ are preserved in $T^{i n d}$.
Question 3.15. Does $T^{\text {ind }}$ eliminate the quantifier $\exists^{\infty}$ ?
We give a partial answer. Namely, we will show the elimination of the $\exists^{\infty} x$ for $L_{H}$-formulas $\phi(x, \vec{z})$ implying $H(\vec{z})$. Note that if $a \in H(M)$ and $\vec{h} \in H(M)$ then $a \in \operatorname{acl}_{H}(\vec{h})$ exactly when $a$ is a part of $\vec{h}$. Thus we may assume that $\phi(x, \vec{z})$ implies $\neg H(x) \wedge H(\vec{z})$. We will be working in a sufficiently saturated $H$-structure $(M, H)$ of a geometric theory $T$.

First, note that if $\vec{h} \in H(M)$ and $|\phi(M, \vec{h})|=n<\omega$, then for any $a \in M$ with $\models \phi(a, \vec{h})$, we have $a \in \operatorname{acl}(\vec{h})$, and there is an $L$-formula $\phi_{n}(x, \vec{z})$ such that $\phi_{n}(M, \vec{h})=\phi(M, \vec{h})$. By compactness, $\phi_{n}(x, \vec{z})$ does not depend on the choice of $\vec{h} \in H(M)$, but it may still depend on $n$ (unless $T$ is $\omega$-categorical). Thus, this approach does not seem to work. Instead, we will take a closer look at the $L_{H^{-}}$-formula $\phi(x, \vec{z})$.

We say that an $L$-formula $\psi(x, \vec{y})$ has a bounded finite number of realizations in $x$, if there exists $n<\omega$ such that for any $\vec{b},|\psi(M, \vec{b})|<n$. Thus, $\phi(x, \vec{b})$ is either inconsistent or witnesses $x \in \operatorname{acl}(\vec{b})$.

Lemma 3.16. For any $\vec{h} \in H(M)$ and $a \in M$ with $a \notin H(M), \operatorname{tp}_{H}(a, \vec{h})$ is axiomatized by $\neg H(x), H(\vec{z})$, L-formulas, and the formulas of the form

$$
\exists \vec{y} \in H \quad \theta(x, \vec{y}, \vec{z})
$$

or

$$
\neg \exists \vec{y} \in H \quad \theta(x, \vec{y}, \vec{z}),
$$

where $\theta(x, \vec{y}, \vec{z})$ is an L-formula having a bounded finite number of realizations in $x$.

Proof. Assuming $a \notin H(M)$ and $\vec{h} \in M$, the $L_{H}$-type of the tuple $a \vec{h}$ is determined by its $L$-type, and either the fact that $a \notin \operatorname{scl}(\vec{h})$ or the $L$-type of some $\vec{k} \in H(M)$ over $\vec{h}$, such that $a \in \operatorname{acl}(\vec{k}, \vec{h})$. All these properties can be expressed with the given types of formulas.

Note that $\phi(x, \vec{z})$ is a conjunction of $H(\vec{z}), \neg H(x)$, Boolean combination of $L$ formulas and formulas of the form $\exists \vec{y} \in H \theta(x, \vec{y}, \vec{z})$, where $\theta(x, \vec{y}, \vec{z})$ is an $L$-formula having a bounded finite number of realizations in $x$. Note that elimination of $\exists^{\infty} x$ is preserved under disjunction. Thus, we may assume that $\phi(x, \vec{z})$ is a conjunction of $H(\vec{z}), \neg H(x)$, an $L$-formula $\Gamma(x, \vec{z})$, and/ or formulas of the form $\exists \vec{y} \in H \theta(x, \vec{y}, \vec{z})$ or $\neg \exists \vec{y} \in H \theta(x, \vec{y}, \vec{z})$, where $\theta(x, \vec{y}, \vec{z})$ is an $L$-formula having a bounded finite number of realizations in $x$. Note that the class of $L$-formulas $\theta(x, \vec{y}, \vec{z})$ having a bounded finite number of realization in $x$ is closed under conjunction and disjunction. Thus, we may assume that $\phi(x, \vec{z})$ has one of the four forms:
(1) $\neg H(x) \wedge H(\vec{z}) \wedge \Gamma(x, \vec{z})$,
(2) $\neg H(x) \wedge H(\vec{z}) \wedge \Gamma(x, \vec{z}) \wedge \exists \vec{y} \in H \quad \theta(x, \vec{y}, \vec{z})$,
(3) $\neg H(x) \wedge H(\vec{z}) \wedge \Gamma(x, \vec{z}) \wedge \neg \exists \vec{y} \in H \theta(x, \vec{y}, \vec{z})$,
(4) $\neg H(x) \wedge H(\vec{z}) \wedge \Gamma(x, \vec{z}) \wedge \exists \vec{y} \in H \theta_{1}(x, \vec{y}, \vec{z}) \wedge \neg \exists \vec{y}^{\prime} \in H \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)$,
where $\Gamma(x, \vec{z})$ is an $L$-formula, and $\theta(x, \vec{y}, \vec{z}), \theta_{1}(x, \vec{y}, \vec{z})$ and $\theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)$ are $L$ formulas having a bounded finite number of realizations in $x$.

Clearly, in cases (1) and (3), the algebraicity of $\phi(x, \vec{h})$ is determined by algebraicity of $\Gamma(x, \vec{z})$. Indeed, in (3), if $\Gamma(x, \vec{h})$ is infinite, it defines a large set, and clearly has an infinite number of realizations that do not satisfy the small formula $\exists \vec{y} \in H \theta(x, \vec{y}, \vec{h})$. Also in cases (2) and (4) we can absorb $\Gamma(x, \vec{z})$ in $\theta(x, \vec{y}, \vec{z})$ or $\theta_{1}(x, \vec{y}, \vec{z})$.

We will now reduce case (4) to case (2). Note that we can assume that $\theta_{1}(x, \vec{y}, \vec{z})$ implies that $\vec{y}$ is a tuple of distinct elements and is disjoint from $\vec{z}$, and $\theta_{2}(x, \vec{y}, \vec{z})$ implies the same about $\vec{y}^{\prime}$.

The idea of the proof is the following. If we assume that $\theta(a, \vec{k}, \vec{h})$ holds for some $\vec{k} \in H(M)$, then to analyze $\exists \vec{y}^{\prime} \in H \quad \theta_{2}\left(a, \vec{y}^{\prime}, \vec{h}\right)$, we will look at the relationship
between $\vec{k}$ and $\vec{y}^{\prime}$, namely, how much of an overlap do we have between $\vec{y}^{\prime}$ and $\vec{k}$. For each subtuple $\vec{k}^{*}$ of $\vec{k}$, we consider all the tuples $\vec{y}^{\prime} \in H(M)$ such that $\vec{y}^{\prime} \cap \vec{k}=\vec{k}^{*}$. It will turn out that the existence of such $\vec{y}^{\prime}$ in $H(M)$ with $\models \theta_{2}\left(a, \vec{y}^{\prime}, \vec{h}\right)$ is (uniformly) $L$-definable in $x \vec{y} \vec{z}$. Then we take the disjunction over all the subtuples of $\vec{y}$.

Claim 1: Let $\vec{h} \in H(M), a \notin H(M)$. Suppose $\vec{k} \in H(M)$ is such that $\models$ $\theta_{1}(a, \vec{k}, \vec{h})$. Let $\vec{k}^{\prime}$ be a subtuple of $\vec{k}$. Suppose $\vec{b} \in H(M)$ is such that $\vec{b} \cap \vec{k}=\vec{k}^{\prime}$ and $\models \theta_{2}(a, \vec{b}, \vec{h})$. Then $a \in \operatorname{acl}\left(\vec{k}^{\prime}, \vec{h}\right)$.

Proof of Claim 1: Since $\models \theta_{2}(a, \vec{b}, \vec{h})$, we have $a \in \operatorname{acl}(\vec{b}, \vec{h})$. On the other hand, $a \in \operatorname{acl}(\vec{k}, \vec{h})$. Since $\vec{b} \vec{h}$ is independent from $\vec{k} \vec{h}$ over $\vec{k}^{\prime} \vec{h}$, we have $a \in \operatorname{acl}\left(\vec{k}^{\prime}, \vec{h}\right)$.

Claim 2: Suppose $\vec{y}^{*}$ is a subtuple of $\vec{y}$. Then the formula

$$
\exists \vec{y}^{\prime} \in H\left(\vec{y}^{\prime} \cap \vec{y}=\vec{y}^{*} \wedge \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)\right)
$$

is equivalent to an $L$-formula $\Delta(x, \vec{y}, \vec{z})$ modulo

$$
H(\vec{z}) \wedge \neg H(x) \wedge H(\vec{y}) \wedge \theta_{1}(x, \vec{y}, \vec{z})
$$

Proof of Claim 2: By Claim 1 and compactness, there exists an $L$-formula $\psi\left(x, \vec{y}^{*}, \vec{z}\right)$ having a bounded finite number of realizations in $x$, such that

$$
\vDash\left(H(\vec{z}) \wedge \neg H(x) \wedge H(\vec{y}) \wedge \theta_{1}(x, \vec{y}, \vec{z}) \wedge \vec{y}^{\prime} \cap \vec{y}=\vec{y}^{*} \wedge \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)\right) \rightarrow \psi\left(x, \vec{y}^{*}, \vec{z}\right)
$$

Let $\vec{y}^{* *}$ be such that $\vec{y}^{\prime}=\vec{y}^{*} \vec{y}^{* *}$ (permute the variables if needed). Then modulo $H(\vec{z}) \wedge \neg H(x) \wedge H(\vec{y}) \wedge \theta_{1}(x, \vec{y}, \vec{z})$,

$$
\exists \vec{y}^{\prime} \in H\left(\vec{y}^{\prime} \cap \vec{y}=\vec{y}^{*} \wedge \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)\right)
$$

is equivalent to

$$
\exists \vec{y}^{* *} \in H\left(\theta_{2}\left(x, \vec{y}^{*} \vec{y}^{* *}, \vec{z}\right) \wedge \psi\left(x, \vec{y}^{*}, \vec{z}\right)\right)
$$

The latter is equivalent, modulo $H(\vec{z}) \wedge \neg H(x) \wedge H\left(\vec{y}^{*}\right) \wedge \vec{y}^{* *} \cap \vec{y}^{*} \vec{z}=\emptyset$ and the statement that $\vec{y}^{* *}$ is a tuple of distinct elements, to the existence of a tuple $\vec{y}^{* *}$, acl-independent over $x \vec{y} \vec{z}$, such that $\theta_{2}\left(x, \vec{y}^{*} \vec{y}^{* *}, \vec{z}\right) \wedge \psi\left(x, \vec{y}^{*}, \vec{z}\right)$ holds true. Indeed, suppose $\vec{h}, \vec{k}^{*} \in H(M), a \notin H(M)$. Note that

$$
\theta_{2}\left(a, \vec{k}^{*} \vec{y}^{* *}, \vec{h}\right) \wedge \psi\left(a, \vec{k}^{*}, \vec{h}\right)
$$

implies that $a \in \operatorname{acl}\left(\vec{k}^{*}, \vec{h}\right)$. Then there exists a tuple of distinct elements $\vec{k}^{* *} \in$ $H(M)$, disjoint from $\vec{k}^{*} \vec{h}$, such that

$$
\models \theta_{2}\left(a, \vec{k}^{*} \vec{k}^{* *}, \vec{h}\right) \wedge \psi\left(a, \vec{k}^{*}, \vec{h}\right)
$$

exactly when there exists a tuple $\vec{k}^{* *} \in M$, acl-independent over $a \vec{k} * \vec{h}$, such that

$$
\models \theta_{2}\left(a, \vec{k}^{*} \vec{k}^{* *}, \vec{h}\right) \wedge \psi\left(a, \vec{k}^{*}, \vec{h}\right)
$$

This condition is $L$-definable in $x \vec{y} \vec{z}$, as needed, which proves Claim 2. Next, rewrite

$$
\neg H(x) \wedge H(\vec{z}) \wedge \exists \vec{y} \in H \quad \theta_{1}(x, \vec{y}, \vec{z}) \wedge \neg \exists \vec{y}^{\prime} \in H \quad \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)
$$

as

$$
\neg H(x) \wedge H(\vec{z}) \wedge \exists \vec{y} \in H\left(\theta_{1}(x, \vec{y}, \vec{z}) \wedge \neg \exists \vec{y}^{\prime} \in H \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)\right),
$$

and note that it is equivalent to

$$
\neg H(x) \wedge H(\vec{z}) \wedge \exists \vec{y} \in H\left(\theta_{1}(x, \vec{y}, \vec{z}) \wedge \neg \bigvee_{\vec{y}^{*} \subset \vec{y}} \exists \vec{y}^{\prime} \in H\left(\vec{y}^{\prime} \cap \vec{y}=\vec{y}^{*} \wedge \theta_{2}\left(x, \vec{y}^{\prime}, \vec{z}\right)\right)\right)
$$

By Claim 2, the disjunction above can be replaced with an $L$-formula in $x \vec{y} \vec{z}$, and therefore can be absorbed in $\theta_{1}(x, \vec{y}, \vec{z})$. This reduces case (4) to case (2). Thus, we may assume that $\phi(x, \vec{z})$ has form

$$
\neg H(x) \wedge H(\vec{z}) \wedge \exists \vec{y} \in H \quad \theta(x, \vec{y}, \vec{z}),
$$

where $\theta(x, \vec{y}, \vec{z})$ is an $L$-formula having a bounded finite number of realizations in $x$.

Lemma 3.17. Suppose $\theta(x, y, \vec{z})$ is an L-formula having a bounded finite number of realizations in $x$. Then for any $\vec{h} \in H(M), \exists y \in H \quad \theta(x, y, \vec{h})$ is infinite if and only if $M \models \exists^{\infty} x \exists y \theta(x, y, \vec{h})$.
Proof. Left to right is clear. For the other direction, suppose $M \models \exists^{\infty} x \exists y \theta(x, y, \vec{h})$. Then we can find a sequence $\left(a_{i}: i \in \omega\right)$ of realizations of $\exists y \theta(x, y, \vec{h})$, aclindependent over $\vec{h}$. For each $a_{i}$ there exists $b_{i} \in M$ such that $M \models \theta\left(a_{i}, b_{i}, \vec{h}\right)$. We have $a_{i} \in \operatorname{acl}\left(b_{i} \vec{h}\right)$. Thus, $b_{i} \notin \operatorname{acl}(\vec{h})$, and $\operatorname{acl}\left(a_{i} \vec{h}\right)=\operatorname{acl}\left(b_{i} \vec{h}\right)$. Then the sequence $\left(b_{i}: i \in \omega\right)$ is also acl-independent over $\vec{h}$, and thus we may assume that $b_{i} \in H(M)$. Then $a_{i}$ all realize $\exists y \in H \theta(x, y, \vec{h})$, as needed.

Lemma 3.18. Suppose $\vec{h} \in H(M), \theta(x, \vec{y}, \vec{z})$ an L-formula having a bounded finite number of realizations in $x$, and implying that $\vec{y}=y_{1} \ldots y_{n}$ is a tuple of distinct elements and $\vec{y} \cap \vec{z}=\emptyset$. Then the formula $\exists \vec{y} \in H \theta(x, \vec{y}, \vec{h})$ is infinite if and only if there exists $1 \leq i \leq n$ and $b_{1}, \ldots b_{i-1}, b_{i+1}, \ldots, b_{n} \in H(M)$ such that

$$
\exists y_{i} \in H \quad \theta\left(x, b_{1}, \ldots, b_{i-1}, y_{i}, b_{i+1}, \ldots, b_{n}, \vec{h}\right)
$$

is infinite.
Proof. Right to left is clear. For the other direction, suppose $\exists \vec{y} \in H \theta(x, \vec{y}, \vec{h})$ is infinite. Then it has infinitely many realizations $a \notin \operatorname{acl}(\vec{h})$. For each such $a$ there exists $\vec{b} \in H$ such that

$$
\models \theta(a, \vec{b}, \vec{h})
$$

Then $a \in \operatorname{acl}(\vec{b}, \vec{h})$. Note that the tuple $\vec{b}$ acl-independent over $\vec{h}$. There is a nonempty minimal subtuple $\vec{b}^{\prime}$ of $\vec{b}$ such that $a \in \operatorname{acl}\left(\overrightarrow{b^{\prime}}, \vec{h}\right)$. Take any $b_{i}$ contained in $\vec{b}^{\prime}$. Then clearly $a$ is interalgebraic (in terms of acl) with $b_{i}$ over $b_{1} \ldots b_{i-1} b_{i+1} \ldots b_{n} \vec{h}$. Taking infinitely many acl-independent $L$-conjugates $a^{\prime} b_{i}^{\prime}$ of $a b_{i}$ over $b_{1} \ldots b_{i-1} b_{i+1} \ldots b_{n} \vec{h}$, with $b_{i} \in H(M)$, we get infinitely many realizations of

$$
\exists y_{i} \in H \theta\left(x, b_{1}, \ldots, b_{i-1}, y_{i}, b_{i+1}, \ldots, b_{n}, \vec{h}\right)
$$

Proposition 3.19. Suppose $\phi(x, \vec{z})$ is an $L_{H}$-formula implying $H(\vec{z})$. Then $\exists^{\infty} x \phi(x, \vec{z})$ is first order.

Proof. We may assume that $\phi(x, \vec{z})$ has form

$$
\neg H(x) \wedge H(\vec{z}) \wedge \exists \vec{y} \in H \quad \theta(x, \vec{y}, \vec{z}),
$$

where $\theta(x, \vec{y}, \vec{z})$ is an $L$-formula having a bounded finite number of realizations in $x$, and $\theta(x, \vec{y}, \vec{z})$ implies that $\vec{y}=y_{1} \ldots y_{n}$ is a tuple of distinct elements, disjoint form $\vec{z}$.

Then by Lemma 3.18, $\exists^{\infty} x \phi(x, \vec{z})$ is equivalent (modulo $\neg H(x) \wedge H(\vec{a})$ ) to

$$
\bigvee_{1 \leq i \leq n} \exists y_{1} \in H \ldots y_{i-1} \in H y_{i+1} \in H \ldots y_{n} \in H \exists^{\infty} x \exists y_{i} \in H \theta(x, \vec{y}, \vec{z})
$$

By Lemma 3.17, $\exists^{\infty} x \exists y \in H \theta(x, \vec{y}, \vec{z})$ is a first order formula.
We finish this section with a property of non-trivial geometric theories that we will use in the next sections.

Definition 3.20. Let $T$ be a geometric theory, let $M \models T$ and let $\vec{a}=\left(a_{1}, \ldots, a_{n-1}, a_{n}\right) \in$ $M^{n}$ be such that $\operatorname{dim}(\vec{a})=n-1$ but any $n-1$ subset of $\left.\left\{a_{1}, \ldots, a_{n-1}, a_{n}\right)\right\}$ is independent. We call such a tuple an algebraic n-gon.

Proposition 3.21. Let $T$ be a non-trivial geometric theory and let $M \models T$ be saturated. Then for every $n$ there is $m \geq n$ and an algebraic $m$-gon.

Proof. Working over a finite independent tuple, if necessary, me may assume that $T$ has an algebraic triangle, i.e. an algebraic 3-gon (triangle) $a b c$. Let $a^{\prime} \models \operatorname{tp}(a / b)$ be independent from $a c$ over $b$. Note that then $a c a^{\prime}$ is an independent tuple. Let $c^{\prime}$ be such that $\operatorname{tp}\left(a^{\prime} c^{\prime} / b\right)=\operatorname{tp}(a c / b)$. Then $a c a^{\prime} c^{\prime}$ is an algebraic 4-gon (quadrangle). Then take $a^{\prime \prime}$ such that $\operatorname{tp}\left(a^{\prime \prime} c^{\prime}\right)=\operatorname{tp}(a c)$ and $a^{\prime \prime}$ is independent from $a b c a^{\prime} c^{\prime}$ over $c^{\prime}$. Then $a c a^{\prime} a^{\prime \prime}$ is an independent tuple. Let $b^{\prime \prime}$ be such that $\operatorname{tp}\left(a^{\prime \prime} b^{\prime \prime} c^{\prime}\right)=\operatorname{tp}(a b c)$. Then $a c a^{\prime} a^{\prime \prime} b^{\prime \prime}$ is an algebraic 5-gon. Continuing in this way, we can generate algebraic $n$-gons for an arbitrarily large $n$.

## 4. Lovely pairs, iterated $H$-structures, and externally definable SETS

In this section we will explore topics motivated by analogies between $H$-structures and lovely pairs. First, we take a closer look at the connections between the two constructions. Then we look at the iterated version of the $H$-structures (similar to "tuples" of structures and "double pairs"). Finally, we look at the expansion of $H(M)$ with traces of externally definable sets.
4.1. Independent subsets and lovely pairs. In this subsection we study the connections between $H$-structures and lovely pairs. Let $T$ be a geometric theory in a language $\mathcal{L}$ and let $N \preceq M \models T$. We say that the pair $(M, N)$ is a lovely pair of models of $T$ if
(1) (Density/coheir property) If $A \subset M$ is finite dimensional and $q \in S_{1}(A)$ is non-algebraic, there is $a \in N$ such that $a \models q$.
(2) (Extension property) If $A \subset M$ is finite dimensional and $q \in S_{1}(A)$ is non-algebraic, there is $a \in M, a \models q$ and $a \notin \operatorname{acl}(A \cup N)$.
Note that the properties characterizing lovely pairs are very similar to the ones of $H$-structures, the role of the independent set $H$ is played by the elementary
substructure $N$. In this section we will only use the definition of lovely pairs. More information on lovely pairs of geometric structures can be found in [3].

Proposition 4.1. Let $T$ be a geometric theory and let $(M, H)$ be an $H$-structure. Let $N=\operatorname{acl}(H)$. Then $(M, N)$ is a lovely pair of models of $T$.

Proof. Let $T,(M, H)$ and $N$ be as above.
Claim $N \preceq M$.
We apply the Tarski-Vaught test. Let $\vec{a} \in N$, let $b \in M$ and assume that $M \models \varphi(b, \vec{a})$. If $b \in \operatorname{acl}(\vec{a})$ then $b \in N$ and $N \models \varphi(b, \vec{a})$. If $b \notin \operatorname{acl}(\vec{a})$ let $p(x)=\operatorname{tp}(b / \vec{a})$. By the coheir property for $H$-structures there is $b^{\prime} \in H$ such that $\operatorname{tp}\left(b^{\prime} / \vec{a}\right)=\operatorname{tp}(b / \vec{a})$

Now we check that $(M, N)$ satisfies the coheir property. Let $A \subset M$ be finite dimensional and let $q \in S_{1}(A)$ be non-algebraic. By the coheir property for $H$ structures, there is $b \in H$ such that $b \models q$. Since $N=\operatorname{acl}(H)$ we have $b \in N$.

Now we check that $(M, N)$ satisfies the extension property. Let $A \subset M$ be finite dimensional and let $q \in S_{1}(A)$ be non-algebraic. By the extension property for $H$ structures, there is $b \in M$ such that $b \models q$ and $b \notin \operatorname{acl}(A \cup H)$. Since $N=\operatorname{acl}(H)$ then $b \notin \operatorname{acl}(A \cup N)$ as desired.

Let $P$ be a new predicate that does not appear in $\mathcal{L}$ and let $L_{P}=L \cup\{P\}$ be the old language extended with a new predicate symbol. If $(M, N)$ is a lovely pair of models of $T$, we can study $(M, N)$ as an $L_{P}$ structure by interpreting $P$ as $N$. In [3] it is shown that if $(M, N)$ and $\left(M^{\prime}, N^{\prime}\right)$ are lovely pairs of models of $T$, then $\operatorname{Th}((M, N))=\operatorname{Th}\left(\left(M^{\prime}, N^{\prime}\right)\right)$ (seen as $L_{P}$ structures). Note that Corollary 2.9 is the analogous result for $H$-structures. We denote by $T_{P}$ this common theory in the language $L_{P}$.

It is shown in [3] that when $T$ is geometric, weakly 1-based, and $\omega$-categorical, then the associated theory $T_{P}$ of lovely pairs is also $\omega$-categorical. This is not the case for the associated theory $T^{i n d}$ :

Example 4.2. Let $T$ be the theory of infinite dimensional vector spaces over a fixed finite field, say $F_{2}$. Note that $T$ is strongly minimal, $\omega$-categorical and 1-based. Let $V \models T$ be countable and let $H=\left\{v_{j}: j \in \omega\right\}$ be an enumeration of a basis. Let $i<\omega$ and let $H_{i}=\left\{v_{j}: j \in \omega, j>i\right\}$. Then $\left(V, H_{i}\right) \models T^{\text {ind }}$ for every $i$ and the models $\left(V, H_{i}\right),\left(V, H_{j}\right)$ are not isomorphic for $i<j$. Thus the theory $T^{\text {ind }}$ is not $\omega$-categorical.

Now let $H_{\text {even }}=\left\{v_{2 j}: j \in \omega\right\}$, then as before $\left(V, H_{\text {even }}\right) \models T^{\text {ind }}$ and it is not isomorphic to any of the pairs $\left(V, H_{i}\right)$. Also note that $\left(V, H_{\text {even }}\right)$ is an $H$-structure, but for every $i \in \omega$ the pair $\left(V, H_{i}\right)$ is NOT an H-structure.

If we take algebraic closures, then we see that for every $i<\omega,\left(V, \operatorname{acl}\left(H_{i}\right)\right)$ is not a model of $T_{p}$, since it does not satisfy the axiom corresponding to the extension property (see the third scheme of axioms in 2.10). On the other hand, $\left(V, \operatorname{acl}\left(H_{\text {even }}\right)\right)$ is a model of $T_{p}$ and it is the unique model up to isomorphism.

The previous example shows:
Remark 4.3. Let $T$ be geometric and let $(M, H) \models T^{\text {ind }}$. Then $(M, \operatorname{acl}(H))$ may not be a model of $T_{P}$. The pair $(M, \operatorname{acl}(H))$ will satisfy the scheme of axioms corresponding to the density property, but it may fail to satisfy the scheme of axioms corresponding to the extension property.
4.2. Iterating the construction: $H$-tuples. In this subsection we show how to iterate the process of expanding by $H$-structures. We will do the details for an expansion with two extra predicates but this procedure can be easily generalized to $n$ tuples of predicates. As before, we start with $T$ a geometric theory in a language $\mathcal{L}$ and we consider $H_{1}, H_{2}$ two new predicate symbols. Let $\mathcal{L}_{2 H}=\mathcal{L} \cup\left\{H_{1}\right\} \cup\left\{H_{2}\right\}$. Let $T^{\prime}$ be the $\mathcal{L}_{H}$-theory of all structures $\left(M, H_{1}, H_{2}\right)$, where $M \models T$ and $H_{1}(M) \cup$ $H_{2}(M)$ is an $\mathcal{L}$-algebraically independent subset of $M$ and $H_{1}(M) \cap H_{2}(M)=\emptyset$.

Definition 4.4. We say that $\left(M, H_{1}(M), H_{2}(M)\right)$ is an $H$-triple if
(1) $(M, H(M)) \models T^{\prime}$
(2) (Density/coheir property for $H_{1}$ ) If $A \subset M$ is finite dimensional and $q \in$ $S_{1}(A)$ is non-algebraic, there is $a \in H_{1}(M)$ such that $a \models q$.
(3) (Density/coheir property for $H_{2} / H_{1}$ ) If $A \subset M$ is finite dimensional and $q \in S_{1}(A)$ is non-algebraic, there is $a \in H_{2}(M)$ such that $a \models q$ and $a \notin \operatorname{acl}\left(A \cup H_{1}(M)\right)$.
(4) (Extension property) If $A \subset M$ is finite dimensional and $q \in S_{1}(A)$ is non-algebraic, there is $a \in M, a \models q$ and $a \notin \operatorname{acl}\left(A \cup H_{1}(M) \cup H_{2}(M)\right)$.

As before, if $\left(M, H_{1}(M), H_{2}(M)\right),\left(N, H_{1}(N), H_{2}(N)\right)$ are $H$-triples, then $T h\left(M, H_{1}(M), H_{2}(M)\right)=$ $T h\left(N, H_{1}(N), H_{2}(N)\right)$, we denote the common theory by $T^{t r i}$.

We will now follow the approach from Fornasiero [16] and consider an $H$-structure associated to the small closure in $\left(M, H_{1}\right)$. Fornasiero [16] considers lovely pairs in a general framework of a closure operator associated to an existential matroid. In this paper we will only consider the special case of the small closure.

Let $T_{2}$ be the $\mathcal{L}_{H}$-theory of all structures $\left(M, H_{1}, H_{2}\right)$, where $\left(M, H_{1}(M)\right)$ is an $H$-structure and $H_{2}(M)$ is an algebraically independent subset of $M$ over $H_{1}(M)=$ $\operatorname{scl}(\emptyset)$.

Definition 4.5. We say that $\left(M, H(M), H_{2}(M)\right)$ is an scl-structure if
(1) $\left(M, H_{1}(M), H_{2}(M)\right) \models T_{2}$
(2) (Density/coheir property for scl) If $A \subset M$ is finite dimensional and $q \in$ $S_{1}^{i n d}(A)$ is non-small, there is $a \in H_{2}(M)$ such that $a \models q$.
(3) (Extension property) If $A \subset M$ is finite dimensional and $q \in S_{1}^{i n d}(A)$ is non-small, there is $a \in M, a \models q$ and $a \notin \operatorname{scl}\left(A \cup H_{2}(M)\right)$.

Now we will show that considering $H$-triples is equivalent as considering sclstructures

Proposition 4.6. Let $T$ be a geometric structure, let $M \models T$ and let $H_{1}(M) \subset M$, $H_{2}(M) \subset M$ be distinguished subsets. Then $\left(M, H_{1}(M), H_{2}(M)\right)$ is a scl-structure if and only if $\left(M, H_{1}(M), H_{2}(M)\right)$ is an $H$-triple.

Proof. Assume first that $\left(M, H_{1}(M), H_{2}(M)\right)$ is a scl-structure. Then the pair $\left(M, H_{1}(M)\right)$ is an $H$-structure and thus $\left(M, H_{1}(M), H_{2}(M)\right)$ satisfies the density/coheir axiom for $H_{1}$. Now let $A \subset M$ be finite dimensional and let $q \in S_{1}(A)$ be non-algebraic. Let $\hat{q} \in S_{1}^{\text {ind }}(A)$ be an extension of $q$ that contains no small formula with parameters in $A$. Then by the Density/coheir property for scl it follows that there is $a \in H_{2}(M)$ such that $a \models \hat{q}$. In particular, $a \models q$ and $a \notin \operatorname{acl}\left(A \cup H_{1}(M)\right)$ and it follows the density/coheir property for $H_{2} / H_{1}$. Finally, since the same $\hat{q}$ is not small, there is $c \in M, c \models \hat{q}$ and $c \notin \operatorname{scl}\left(A \cup H_{2}(M)\right)=\operatorname{acl}\left(A \cup H_{1}(M) \cup H_{2}(M)\right)$. Thus the extension property $H$-triples holds.

Now assume that $\left(M, H_{1}(M), H_{2}(M)\right)$ is an $H$-triple. By the density property for $H_{1}$ and the extension property it follows that $\left(M, H_{1}(M)\right)$ is an $H$-structure and that $\left(M, H_{1}(M), H_{2}(M)\right) \models T_{2}$. Now let $A \subset M$ be finite dimensional and let $\hat{q} \in S_{1}^{\text {ind }}(A)$ be non-small. We may enlarge $A$ and assume that $A=A \cup H B(A)$, so that $A$ is $H_{1}$-independent. Let $q$ be the restriction of $\hat{q}$ to the language $\mathcal{L}$. Note that $\hat{q}$ is the unique extension of $q$ to a non-small type. By the density/coheir property for $H_{2} / H_{1}$ there is $a \in H_{2}(M)$ such that $a \models q, a \notin \operatorname{acl}\left(H_{1} A\right)$ and thus $a \models \hat{q}$. Finally the extension property follows from the extension property for $H$-triples.

We will now show that the class of scl-structures is "first order", that is, that there is a set of axioms whose $|T|^{+}$-saturated models are the scl-structures. For this we consider $H$-triples.

Proposition 4.7. Assume $T$ eliminates $\exists^{\infty}$. Then the theory $T^{t r i}$ is axiomatized by:
(1) $T^{\prime}$.
(2) For all $\mathcal{L}$-formulas $\varphi(x, \vec{y})$ $\forall \vec{y}\left(\varphi(x, \vec{y})\right.$ nonalgebraic $\left.\Longrightarrow \exists x\left(\varphi(x, \vec{y}) \wedge x \in H_{1}\right)\right)$.
(3) For all $\mathcal{L}$-formulas $\varphi(x, \vec{y}), m \in \omega$, and all $\mathcal{L}$-formulas $\psi\left(x, z_{1}, \ldots, z_{m}, \vec{y}\right)$ such that for some $n \in \omega \forall \vec{z} \forall \vec{y} \exists \leq n x \psi(x, \vec{z}, \vec{y}) \quad($ so $\psi(x, \vec{y}, \vec{z})$ is always algebraic in $x$ )
$\forall \vec{y}\left(\varphi(x, \vec{y})\right.$ nonalgebraic $\Longrightarrow \exists x\left(\varphi(x, \vec{y}) \wedge x \in H_{2}\right) \wedge$
$\left.\forall w_{1} \ldots \forall w_{m} \in H_{1} \neg \psi\left(x, w_{1}, \ldots, w_{m}, \vec{y}\right)\right)$
(4) For all $\mathcal{L}$-formulas $\varphi(x, \vec{y}), m \in \omega$, and all $\mathcal{L}$-formulas $\psi\left(x, z_{1}, \ldots, z_{m}, \vec{y}\right)$ such that for some $n \in \omega \forall \vec{z} \forall \vec{y} \exists \leq n x \psi(x, \vec{z}, \vec{y})$ (so $\psi(x, \vec{y}, \vec{z})$ is always algebraic in $x$ )
$\forall \vec{y}\left(\varphi(x, \vec{y})\right.$ nonalgebraic $\Longrightarrow \exists x\left(\varphi(x, \vec{y}) \wedge x \notin H_{1} \wedge x \notin H_{2}\right) \wedge$ $\left.\forall w_{1} \ldots \forall w_{m} \in H_{1} \cup H_{2} \neg \psi\left(x, w_{1}, \ldots, w_{m}, \vec{y}\right)\right)$

Furthermore, if $\left(M, H_{1}(M), H_{2}(M)\right) \models T^{t r i}$ is $|T|^{+}$-saturated, then $\left(M, H_{1}(M), H_{2}(M)\right)$ is an $H$-triple.

The proof is the same one as for $H$-structures and we leave it for the reader.
Note that since $T$ eliminates the quantifier $\exists^{\infty}$, then $T^{i n d}$ eliminates the quantifier $\exists^{\text {large }}$. This is the main reason why the theory of $H$-triples is axiomatizable.
4.3. Elimination of $\exists y \in H$. In this subsection we will look at elimination of quantifiers in the structure obtained by naming all the externally definable relations on $H(M)$ in an $H$-structure (note we have already shown any $\mathcal{L}_{H}$-definable relation on $H(M)$ is $\mathcal{L}$-definable). This problem is known as elimination of $\exists y \in P$, where $P$ is a unary predicate symbol. Such an elimination is known to hold in the case when $P$ is an elementary submodel of a model of a stable theory (by definability of types), or an elementary submodel of a sufficiently saturated model of an NIP theory (established by Shelah [25]). The case when $P$ is the smaller model in a lovely pair of models of a simple theory has been considered in [22], where the elimination of $\exists y \in P$ has been shown to be equivalent to the property called weak lowness. In the case of lovely pairs of geometric structures, the elimination of $\exists y \in P$ was shown in [3]. Here we will show that any $H$-structure of a geometric theory eliminates $\exists y \in H$.

We will follow the Definition 1.1 from [22].

Definition 4.8. Let $T$ be a first order theory in a language $\mathcal{L}$, and let $(M, H)$ be an expansion of $M$ with a new unary predicate. We say that $(M, H)$ eliminates the quantifier $\exists y \in H$, if for any $\mathcal{L}$-formula $\phi(\vec{x}, y, \vec{z})$ and $\vec{a} \in M$, there exists an $\mathcal{L}$-formula $\psi(\vec{x}, \vec{w})$ and $\vec{b} \in M$, such that for any $\vec{c} \in H(M)$,

$$
(M, H) \models \exists y \in H \phi(\vec{c}, y, \vec{a}) \Longleftrightarrow M \models \psi(\vec{c}, \vec{b})
$$

If the choice of $\psi(\vec{x}, \vec{w})$ does not depend on the choice of $\vec{a} \in M$ (i.e. depends only of the formula $\phi(\vec{x}, y, \vec{y})$ ), we say that the elimination is uniform.
Proposition 4.9. Let $T$ be a geometric theory, and let $(M, H)$ be an $H$-structure of $T$. Then $(M, H)$ eliminates the quantifier $\exists y \in H$.
Proof. Let $\phi(\vec{x}, y, \vec{z})$ be an $\mathcal{L}$-formula, and let $\vec{a} \in M$. Let $\vec{c} \in H(M)$.
If the formula $\phi(\vec{c}, y, \vec{a})$ is non-algebraic, then clearly, it is realized in $H(M)$.
Now, suppose the formula $\phi(\vec{c}, y, \vec{a})$ is algebraic and is realized by $e \in H(M)$, where $e$ is not a part of the tuple $\vec{c}$. Let $\vec{d}=H B(\vec{a})$, viewed as a tuple. If $e$ is not a part of $\vec{d}$, then $e$ is not algebraic over $\vec{c} \vec{d}$, and thus $\vec{c} e \not_{\vec{d}} \vec{a}$. This contradicts the definition of $H B(\vec{a})$. Thus $e$ is a part of $\vec{d}$.

Thus for any $c \in H(M)$, we have $(M, H) \models \exists y \in H \phi(c, y, \vec{a})$ if and only if either $\phi(\vec{c}, y, \vec{a})$ is non-algebraic,
or $M \models \phi(\vec{c}, e, \vec{a})$ where $e$ is a part of $\vec{c} H B(\vec{a})$.
Both conditions on $\vec{c}$ are $\mathcal{L}$-definable over the elements of $\vec{a} H B(\vec{a})$.

Question 4.10. Is this elimination uniform? Note that the $\mathcal{L}$-definition of $\exists y \in$ $H \phi(\vec{c}, y, \vec{a})$ involves $H B(\vec{a})$, and this tuple could be arbitrarily long.

## 5. Strongly minimal, $S U$-Rank 1 and thorn rank 1 cases

In this section we study four special cases of geometric theories, when the underlying theory $T$ is strongly minimal, $S U$-rank 1 , thorn rank 1 or strongly dependent of finite dp-rank. In these cases, we show that the theory $T^{\text {ind }}$ becomes $\omega$-stable, supersimple of $S U$-rank less than or equal to $\omega$, super-rosy of thorn-rank less than or equal to $\omega$ or strongly dependent respectively. We also characterize in each of these cases when $T$ is trivial in terms of the rank of $T^{i n d}$.
5.1. Strongly minimal case. Let $T$ be a strongly minimal theory (in particular it is a geometric theory). In this section we prove that $T^{i n d}$ is $\omega$-stable and has Morley rank less than or equal to $\omega$.
Proposition 5.1. Let $T$ be strongly minimal. Then $T^{i n d}$ is $\omega$-stable.
Proof. Suppose $(M, H(M))$ is a sufficiently saturated model of $T^{i n d}$, and $A \subset M$ is a countable set. We may assume that $A$ is $H$-independent. We will count the number of types of the form $\operatorname{tp}_{H}(b / A)$ where $b \in M$.

Case 1: $b \in H(M)$. Then $b A$ is $H$-independent, and $\operatorname{tp}_{H}(b / A)$ is determined by $\operatorname{tp}(b / A)$ and the fact that $b \in H(M)$. By strong minimality of $T$, there are at most countably many such types.

Case 2: $b \in \operatorname{scl}(A)$. Then there are $h_{1}, \ldots, h_{l} \in H(M)$ such that $b \in \operatorname{acl}\left(h_{1} \ldots h_{l} A\right)$. By Case 1 , there are at most countably many types of the form $\operatorname{tp}_{H}\left(h_{1}, \ldots, h_{l} / A\right)$ where $h_{i} \in H(M)$, and thus at most countably many types of the form $\operatorname{tp}_{H}(b / A)$ for $b$ as above.

Case 3: $b \notin \operatorname{scl}(A)$. Note that $b A$ is $H$-independent, and thus $\operatorname{tp}_{H}(b / A)$ is determined by $\operatorname{tp}_{H}(b / A)$ and the fact that $b \notin \operatorname{scl}(A)$. There is a unique such type.

In the setting of lovely pairs of strongly minimal theories, there is a strong connection between the underlying geometry of the theory $T$ and the Morley rank of the associated theory of lovely pairs $T_{P}$. Buechler [9] showed that $T$ is trivial iff $M R\left(T_{P}\right)=1, T$ is locally modular non-trivial iff $M R\left(T_{P}\right)=2$ and $T$ is not locally modular iff $M R\left(T_{P}\right)=\omega$. He used this result to prove that pseudolinearity implies linearity. We will now show that the Morley rank of the theory $T^{\text {ind }}$ "detects" trivial theories, in the sense that $T$ is trivial iff $M R\left(T^{i n d}\right) \leq 2$ and non-trivial iff $M R\left(T^{\text {ind }}\right)=\omega$.
Proposition 5.2. Let $T$ be strongly minimal and trivial (i.e $\operatorname{acl}(A)=\bigcup_{a \in A} \operatorname{acl}(a)$ ). Let $(M, H) \models T^{\text {ind }}$. Then $T^{\text {ind }}$ has Morley rank 1 iff for all $a \in M, a \notin \operatorname{acl}(\emptyset)$, $\operatorname{acl}(a) \backslash \operatorname{acl}(\emptyset)$ is finite. Otherwise, $T$ has Morley rank 2.

Proof. Let $(M, H)$ be a sufficiently saturated model of $T^{i n d}$. Note that because of triviality, $\operatorname{acl}_{H}=\operatorname{acl}$ in $(M, H)$.

Let $b \in H(M)$. Note for any (small) $A \subset M$, there is a unique non-algebraic $L_{H}$-type of an element of $H(M)$ over $A$. Thus $M R(b)=1$. This shows that $M R(H(x))=1$.

Now, let $b \notin H(M)$. Let $A$ be a small subset of $M$. If $b \in \operatorname{scl}(A)$, by triviality of $T$, either $b \in \operatorname{acl}(A)$, in which case, $M R(b / A)=0$, or $b \in \operatorname{acl}(h) \backslash \operatorname{acl}(A)$ for some $h \in H(M)$. Note also that $h \in \operatorname{acl}(b)$. Then $M R(b / A)=M R(h / A)=M R(h)=1$. This shows that Morley rank of any small definable set in $(M, H)$ is $\leq 1(=1$ if the set is infinite).

Note that any two large definable sets in $(M, H)$ have a large intersection, so there is a unique large type. It follows that $T^{i n d}$ has Morley rank $\leq 2$.

Suppose $\operatorname{acl}(a) \backslash \operatorname{acl}(\emptyset)$ is finite for all non-algebraic $a \in M$, say of size $n$. Let $\theta(x)$ be the first order formula expressing " $x \in \operatorname{acl}(h) \backslash \operatorname{acl}(\emptyset)$ for some $h \in H(M)$ ". Then $\theta(x)$ has $n$ non-algebraic extensions over any small $A \subset M$. Since there is a unique large type over $A$, there are only finitely many non-algebraic types over $A$. Thus, in this case $T^{i n d}$ has Morley rank 1.

Suppose $\operatorname{acl}(a) \backslash \operatorname{acl}(\emptyset)$ is infinite for all non-algebraic $a \in M$. Then we can find $L$-formulas $\phi_{n}(x, y), n \in \omega$, such that for $a \in M \backslash \operatorname{acl}(\emptyset)$, we have $\phi_{n}(M, a) \subset$ $\operatorname{acl}(a) \backslash \operatorname{acl}(\emptyset)$, and $\phi_{n}(M, a)$ are finite, disjoint and non-empty. Let $\psi_{n}(x)=\exists y \in$ $H \phi_{n}(x, y)$. Then $\psi_{n}(M)$ are infinite and small. From the disjointness of $\phi_{n}(M, a)$ for a fixed $a$ and independence of $H(M)$ it follows that $\psi_{n}(M)$ are disjoint. Thus, in this case, $T^{i n d}$ has Morley rank 2.

Proposition 5.3. Let $T$ be strongly minimal and non-trivial. Then $T^{i n d}$ has Morley rank $\omega$.

Proof. Suppose $(M, H(M))$ is sufficiently saturated model of $T^{i n d}$, and $A \subset M$ is a countable set. We may assume that $A$ is $H$-independent. Let $b \in M$.

Case 1: $b \in H(M)$. Then $b A$ is $H$-independent, and $\operatorname{tp}_{H}(b / A)$ is determined by $\operatorname{tp}(b / A)$ and the fact that $b \in H(M)$. In this case $M R(b / A) \leq 1$.

Case 2: $b \in \operatorname{scl}(A)$. Then there are $h_{1}, \ldots, h_{l} \in H(M)$ such that $b \in \operatorname{acl}\left(h_{1} \ldots h_{l} A\right)$. We may assume that $l$ is minimal. Then $b$ is $\mathcal{L}_{H}$-interalgebraic with $h_{1} \ldots h_{l}$ over
$A$. Thus $M R(b / B)=M R\left(h_{1} \ldots h_{l} / A\right)=l$. Since $T$ is not trivial, by Proposition 3.21 for every $n$ there exists an algebraic $n$-gon $a_{1}, \ldots, a_{n-1}, a_{n}$, and we can assume that $a_{1}, \ldots, a_{n-1} \in H(M)$ (and thus $\left.a_{n} \notin H\right)$. We may also assume that $a_{1} \ldots a_{n}$ is independent from $A$ over $\emptyset$. Thus for any $b \in \operatorname{scl}(A), M R(b / A)<\omega$ but can have arbitrarily large finite values.

Case 3: $b \notin \operatorname{scl}(A)$. As noted in the proof of Proposition 5.1, there a unique such 1-type over $A$. Then $M R(b / A) \leq \omega$. Since $T$ is not trivial, for every $n$ there exists an algebraic $n+2$-gon $a_{1}, \ldots, a_{n+2}$, where $a_{n+2}=b, a_{n+1} \notin H(M), a_{1}, \ldots, a_{n} \in H(M)$ and $a_{1} \ldots a_{n+2}$ is independent from $A$ over $\emptyset$. Then $\operatorname{tp}_{H}\left(b / a_{1} \ldots a_{n+1} A\right)$ has Morley rank $n$. Therefore $M R(b / A) \geq \omega$. Thus $M R(b / A)=\omega$.

Next we will take a look at the geometric properties of $T^{i n d}$. It is well-known that in case of lovely pairs (or belles paires, in the stable case), if $T$ is one-based, then so is the pair theory $T_{P}$. This is no longer the case for $T^{i n d}$, as the following example illustrates.

Example 5.4. Let $(V,+, 0, H)$ be a vector space over $\mathbb{Q}$, where $H(V)=\left\{v_{i}\right.$ : $i \in \omega\}$ consists of linearly independent vectors over $\mathbb{Q}$. Furthermore assume that $V \neq \operatorname{span}\left(\left\{v_{i}: i \in \omega\right\}\right)$. Then $\left(V,+, 0,\left\{v_{i}: i \in \omega\right\}\right) \models T^{\text {ind }}$ where $T$ is the theory of vector spaces over $\mathbb{Q}$. Let $u \in V \backslash \operatorname{span}\left(\left\{v_{i}: i \in \omega\right\}\right)$. Note that $u$ being generic is $H$-independent and that $\operatorname{acl}_{H}(u)=\operatorname{span}(u)$. Let $t=u+v_{1}$.

Claim $T^{\text {ind }}$ is not 1-based.
Note that $t$ is small over $u$, $t$ is interdefinable with $v_{1}$ over $u$ and that $M R(\operatorname{tp}(t / u))=$ 1. Let $t^{\prime}=u+v_{2}$, then $\operatorname{tp}_{H}\left(v_{1} / u\right)=\operatorname{tp}_{H}\left(v_{2} / u\right)$ (since they are $H$-independent) and thus $\operatorname{tp}_{H}(t / u)=\operatorname{tp}_{H}\left(t^{\prime} / u\right)$. Note that $t \downarrow_{u}^{\text {ind }} t^{\prime}$. Note also that $t-t^{\prime}=v_{1}-v_{2}$ so $t$ is interdefinable with $\left\{v_{1}, v_{2}\right\}$ over $t^{\prime}$. Thus $M R\left(\operatorname{tp}_{H}\left(t / t^{\prime}\right)\right)=2$ and thus $t \mathbb{X}_{t^{\prime}}^{\text {ind }} u$. Hence $T^{\text {ind }}$ is not 1-based.

Carmona showed in [10] that when $T$ is linear, $T^{i n d}$ is CM-trivial.
5.2. SU-rank one theories. Let $T$ be an $S U$-rank one theory.

Theorem 5.5. The theory $T^{i n d}$ is supersimple.
Proof. We will prove that non-dividing has local character.
Let $(M, H(M)) \models T^{i n d}$ be saturated. Let $C \subset D \subset M$ be small sets and assume that $C=\operatorname{acl}_{H}(C)$ and $D=\operatorname{acl}_{H}(D)$. Note that both $C$ and $D$ are $H$-independent. Let $\vec{a} \in M$. We will find "geometric conditions" for the type of $\vec{a}$ over $C$ and $D$ that guarantee that $\operatorname{tp}_{H}(\vec{a} / D)$ does not divide over $C$.

We may write $\vec{a}=\left(\vec{a}_{1}, \vec{a}_{2}, \vec{a}_{3}\right) \in M$ so that $\vec{a}_{1}$ is an independent tuple over $C H$, $\vec{a}_{2}$ is an independent tuple over $C \vec{a}_{1}, \vec{a}_{2} \in \operatorname{acl}\left(H C \vec{a}_{1}\right)$ and $\vec{a}_{3} \in \operatorname{acl}\left(C \vec{a}_{1} \vec{a}_{2}\right)$. Assume that $\vec{a}_{1}$ is an independent tuple over $D H$ and that $H B(\vec{a} / D)=H B(\vec{a} / C)$.

Claim $\operatorname{tp}_{H}(\vec{a} / D)$ does not divide over $C$.
Let $p(\vec{x}, D)=\operatorname{tp}\left(\vec{a}_{1}, D\right)$. Let $\left\{D_{i}: i \in \omega\right\}$ be an $\mathcal{L}_{H}$-indiscernible sequence over $C$. Since $\vec{a}_{1}$ is independent over $D, \operatorname{tp}\left(\vec{a}_{1}, D\right)$ does not divide over $C$ and $\cup_{i \in \omega} p\left(\vec{x}, D_{i}\right)$ is consistent. We can find $\vec{a}_{1}^{\prime} \models \cup_{i \in \omega} p\left(\vec{x}, D_{i}\right)$ such that $\left\{\vec{a}_{1}^{\prime} D_{i}: i \in \omega\right\}$ is indiscernible and $\vec{a}_{1}^{\prime}$ is independent over $\cup_{i \in \omega} D_{i}$. By the generalized extension property, we may assume that $\vec{a}_{1}^{\prime}$ is independent over $\cup_{i \in \omega} D_{i} H$. Note that $\vec{a}_{1} D$ is $H$-independent, $\vec{a}_{1} D_{i}$ is also $H$-independent for any $i \in \omega$. So by Lemma 2.8 $\operatorname{tp}_{H}\left(\vec{a}_{1} D\right)=\operatorname{tp}_{H}\left(\vec{a}_{1}^{\prime} D_{i}\right)$ for any $i \in \omega$.

Now let $\vec{h}=H B(\vec{a} / C)$ (viewed as a tuple) and let $q\left(\vec{y}, \vec{a}_{1}, D\right)=\operatorname{tp}\left(\vec{h}, \vec{a}_{1}, D\right)$. Note that $\vec{h}$ is an independent tuple over $\vec{a}_{1} D$ (as well as an independent tuple over $\left.\vec{a}_{1} C\right)$. Since $\left\{D_{i} a_{1}^{\prime}: i \in \omega\right\}$ is an $\mathcal{L}$-indiscernible sequence, there is $\vec{h}^{\prime} \models \cup_{i \in \omega} q\left(\vec{y}, \vec{a}_{1}^{\prime}, D_{i}\right)$. We may assume that $\vec{h}^{\prime}$ is independent from $\cup_{i \in \omega} D_{i} a_{1}^{\prime}$. By the generalized coheir/density property, we may assume that $\vec{h}^{\prime} \in H$. Note that since each $\vec{a}_{1}^{\prime} D_{i}$ is $H$-independent, then $\vec{h}^{\prime} \vec{a}_{1}^{\prime} D_{i}$ is also $H$-independent. On the other hand, $\operatorname{tp}\left(\vec{h}, \vec{a}_{1}, D\right)=\operatorname{tp}\left(\vec{h}^{\prime}, \vec{a}_{1}^{\prime}, D_{i}\right)$ for each $i$, so by Lemma 2.8 we have $\operatorname{tp}_{H}\left(\vec{h}, \vec{a}_{1}, D\right)=\operatorname{tp}_{H}\left(\vec{h}^{\prime}, \vec{a}_{1}^{\prime}, D_{i}\right)$. This shows that $\operatorname{tp}\left(\vec{a}_{1}, \vec{h} / D\right)$ does not divide over $C$ and since $\vec{a} \in \operatorname{acl}\left(\vec{a}_{1}, \vec{h} C\right)$ we get that $\operatorname{tp}(\vec{a} / D)$ does not divide over $C$.

Since for any $D$ and $\vec{a}$ we can always choose a countable set $C$ with the properties described above, $T$ is simple.

Given any $D=\operatorname{acl}_{H}(D)$ and a tuple $\vec{a} \in M$, write $\vec{a}=\left(\vec{a}_{1}, \vec{a}_{2}, \vec{a}_{3}\right) \in M$ so that $\vec{a}_{1}$ is an independent tuple over $D H, \vec{a}_{2}$ is an independent tuple over $D \vec{a}_{1}$, $\vec{a}_{2} \in \operatorname{acl}\left(H D \vec{a}_{1}\right)$ and $\vec{a}_{3} \in \operatorname{acl}\left(D \vec{a}_{1} \vec{a}_{2}\right)$. We can always choose a finite $B \subset D$ such that for $C=\operatorname{acl}_{H}(B)$ we have $H B(\vec{a} / C)=H B(\vec{a} / D)$ and $\vec{a}_{3} \in \operatorname{acl}\left(C, \vec{a}_{1}, \vec{a}_{2}\right)$. Then $\operatorname{tp}(\vec{a} / D)$ does not divide over $B$ and $T$ is supersimple.

Proposition 5.6. Let $(M, H) \models T^{\text {ind }}$ be saturated, let $C \subset D \subset M$ be small and such that $C=\operatorname{acl}_{H}(C), D=\operatorname{acl}_{H}(D)$ and let $a \in M$. Then $\operatorname{tp}(a / D)$ forks over $C$ iff $a \in D \backslash C$ or $a \in \operatorname{scl}(D) \backslash \operatorname{scl}(C)$ or $H B(a / C) \neq H B(a / D)$.
Proof. In the proof of Theorem 5.5 we showed that if $a \in C$ or if $H B(a / C)=$ $H B(a / D)$ then $\operatorname{tp}(a / D)$ does not fork over $C$. So it remains to show the other direction, which we do case by case.

Case 1: Assume that $a \in D \backslash C$, then $a$ became algebraic over $D$ and $\operatorname{tp}(a / D)$ forks over $C$.

Case 2: Assume that $a \in \operatorname{scl}(D) \backslash \operatorname{scl}(C)$. Let $\vec{d} \in D$ and let $\vec{c} \in C$ be such that $a \in \operatorname{acl}(\vec{c} \vec{d} H)$. We can choose $\vec{d}$ independent over $H C$. Let $\vec{h} \in H$ be such that $a \in \operatorname{acl}(\vec{c} d \vec{h})$. Let $p(x, \vec{y})=t p_{H}(a, \vec{d} / C)$.

Let $\left\{\vec{d}_{i}: i \in \omega\right\}$ be an $\mathcal{L}$-indiscernible sequence in $\operatorname{tp}(\vec{d} / C)$ over $C$ such that $\left\{\vec{d}_{i}: i \in \omega\right\}$ is independent over $C$. By the generalized extension property, we may assume that $\left\{\vec{d}_{i}: i \in \omega\right\}$ is independent over $H C$. Note that by Lemma 2.8 $\left\{\vec{d}_{i}: i \in \omega\right\}$ is an $\mathcal{L}_{H}$-indiscernible sequence over $C$. Assume, in order to get a contradiction, that there is $a^{\prime} \models \cup_{i \in \omega} p\left(x, \vec{d}_{i}\right)$. Then there are $\left\{\vec{h}_{i}: i \in \omega\right\}$ such that $a^{\prime} \in \operatorname{acl}\left(\overrightarrow{d_{i}}, \vec{c}, \vec{h}_{i}\right)$ for every $i$. But $a^{\prime} \notin \operatorname{acl}(C H)$, so ${\overrightarrow{d_{0}}}_{\mathbb{X}_{C H}} \overrightarrow{d_{1}}$, a contradiction.

Case 3: Assume that $H B(a / D) \neq H B(a / C)$. Then $H B(a / D)$ is a proper subset of $H B(a / C)$. Write $\vec{h}_{C}=H B(a / C), \vec{h}_{D}=H B(a / D)$ and let $\vec{h}_{E} \in H$ be such that $\vec{h}_{C}=\vec{h}_{D} \vec{h}_{E}$. Note that $\vec{h}_{E} \neq \emptyset$ and that $\vec{h}_{E} \in D$ is an independent tuple over $C$.

Let $p(x, \vec{y})=\operatorname{tp}_{H}\left(a, \vec{h}_{E} / C\right)$. Let $\left\{\vec{h}_{E}^{i}: i \in \omega\right\}$ be an indiscernible sequence in $\operatorname{tp}\left(\vec{h}_{E} / C\right)$ such that $\left\{\vec{h}_{E}^{i}: i \in \omega\right\}$ is independent over $C$. Then by the generalized density property, we may assume that the sequence $\left\{\vec{h}_{E}^{i}: i \in \omega\right\}$ belongs to $H$. Note that by Lemma 2.8, the sequence $\left\{\vec{h}_{E}^{i}: i \in \omega\right\}$ is indiscernible over $C$. We will show that $\cup_{i \in \omega} p\left(x, \vec{h}_{E}^{i}\right)$ is inconsistent.

Assume, not, so there is $a^{\prime} \models \cup_{i \in \omega} p\left(x, \vec{h}_{E}^{i}\right)$. Then we can find $\vec{h}_{D_{i}}$ in $H$ such that $H B\left(a^{\prime} / C\right)=\vec{h}_{D_{i}} \vec{h}_{E}^{i}$. Since the $h_{E}^{i}$ are independent, we get that the $H$-basis of $a^{\prime}$ over $C$ is not unique, a contradiction.

Corollary 5.7. Let $(M, H) \models T^{\text {ind }}$ be saturated, let $C \subset M$ be small and such that $C=\operatorname{acl}_{H}(C)$ and let $a \in H(M)$. Then $S U(a / C) \leq 1$.
Proof. Clearly $S U(a / C)=0$ iff $a \in C$. If $a \notin C$, then $H B(a / C)=\{a\}$ so if it forks over some superset $D$ of $C$ by Proposition 5.6 we must have that $H B\left(a / \operatorname{acl}_{H}(D)\right)=$ $\emptyset$ and that means that $a \in \operatorname{acl}_{H}(D)$.
Corollary 5.8. Let $T$ be non-trivial and let $(M, H) \models T^{\text {ind }}$ be saturated, let $C \subset M$ be small such that $C=\operatorname{acl}_{H}(C)$ and let $a \in M$. Then
(1) $a \in C$ iff $S U\left(\operatorname{tp}_{H}(a / C)\right)=0$
(2) $a \in \operatorname{scl}(C)$ iff $S U\left(\operatorname{tp}_{H}(a / C)\right)<\omega$ and $S U\left(\operatorname{tp}_{H}(a / C)\right)=|H B(a / C)|$.
(3) $a \notin \operatorname{scl}(C)$ iff $S U\left(\operatorname{tp}_{H}(a / C)\right)=\omega$.

Proof. If $a \in \operatorname{scl}(C)$, then $a$ is interalgebraic with $H B(a / C)$ over $C$. By Corollary 5.7, $S U\left(\operatorname{tp}_{H}(H B(a / C) / C)\right)=|H B(a / C)|$ and thus $S U\left(\operatorname{tp}_{H}(a / C)\right)=|H B(a / C)|$. Since $T$ is not trivial, there are algebraic $n$-gons for $n$ large enough and thus we can get arbitrarily large values for $S U(a / C)$. If $a \notin s c l(C)$, then by Proposition 5.6 and the existence of algebraic $n$-gons for $n$ large enough shows that $S U(\operatorname{tp}(a / C))=\omega$. The other statements are clear.

Corollary 5.9. Let $T$ be trivial and let $(M, H) \models T^{\text {ind }}$ be saturated, let $C \subset M$ be small such that $C=\operatorname{acl}_{H}(C)$ and let $a \in M$. Then
(1) $a \in C$ iff $S U(a / C)=0$
(2) If $a \in \operatorname{scl}(C) \backslash C$ then $S U\left(\operatorname{tp}_{H}(a / C)\right)=1$.
(3) If $a \notin \operatorname{scl}(C)$ then $S U\left(\operatorname{tp}_{H}(a / C)\right)=1$.

Proof. The first statement is clear. If $a \in \operatorname{scl}(C) \backslash C$ then by triviality of $T$ there is a single $h \in H$ such that $a \in \operatorname{acl}(h)$ and by Corollary 5.7 $S U(a / C)=S U(h / C)=1$. If $a \notin \operatorname{scl}(C)$ and $D$ is a superset of $C$ such that $\operatorname{tp}_{H}(a / D)$ forks over $C$, then by Proposition 5.6 and triviality we must have that $a \in \operatorname{acl}_{H}(D)$.

Remark 5.10. Note that in the case when $T$ is strongly minimal, the behavior of Morley rank maybe different form that of the SU-rank (U-rank). Namely, as we showed in Proposition 5.3, for a trivial strongly minimal theory $T$ where $\operatorname{acl}(a) \backslash \operatorname{acl}(\emptyset)$ is infinite for $a \notin \operatorname{acl}(\emptyset)$, the theory $T^{\text {ind }}$ has Morley rank 2 (while its U-rank is 1).
Corollary 5.11. (Coordinatization) Let $(M, H) \models T^{\text {ind }}$ be $\kappa$-saturated, let $C \subset M$ be such that $C=\operatorname{acl}_{H}(C),|C|<\kappa$ and let $\vec{a} \in M^{n}$. Write $\vec{a}=\vec{a}_{1} \vec{a}_{2} \vec{a}_{3}$ where $\vec{a}_{1}$ is algebraically independent over HC, $\vec{a}_{2}$ is algebraically independent over $C \vec{a}_{1}$ and $\vec{a}_{2} \in \operatorname{scl}\left(C \vec{a}_{1}\right)$ and $\vec{a}_{3} \in \operatorname{acl}\left(\vec{a}_{1} \vec{a}_{2} C\right)$. Then for every $e \in \vec{a}_{1}, \operatorname{tp}_{H}(e / C)$ is regular, $\vec{a}_{2}$ is interalgebraic with $H B(\vec{a} / C)$ over $C \vec{a}_{1}$ and for each $h \in H B(\vec{a} / C), \operatorname{tp}_{H}\left(h / C \vec{a}_{1}\right)$ is regular. So there is an explicit coordinatization in $T^{\text {ind }}$ in terms of types of real elements.

Our next goal is to describe canonical bases in $T^{\text {ind }}$, for any SU-rank 1 theory $T$. Note that since $T^{i n d}$ is supersimple, it eliminates hyperimaginaries, so canonical bases exist as imaginaries, both in $T$ and $T^{\text {ind }}$. Let $C b(\vec{a} / B)$ denote $C b(\operatorname{stp}(\vec{a} / B))$, and $C b_{H}(\vec{a} / B)$ denote $C b\left(\operatorname{stp}_{H}(\vec{a} / B)\right)$.
Lemma 5.12. Let $(M, H)$ be a sufficiently saturated $H$-structure of $T, B \subset M$ an $H$-independent set, and $\vec{a} \in M, h=H B(\vec{a} / B)$ (viewed as an imaginary representing a finite set). Suppose $e \in \operatorname{acl}^{e q}(B)$ (in the original theory) is such that $\vec{a} h \downarrow_{e} B$. Then $\vec{a} \downarrow_{e}^{\text {ind }} B$.

Proof. We may assume that $\vec{a}=\vec{a}_{1} \vec{a}_{2} \vec{a}_{3}$, where $\vec{a}_{1}$ acl-independent over $B \cup H(M)$, $\vec{a}_{2} \in \operatorname{acl}\left(H(M) B \vec{a}_{1}\right) \backslash \operatorname{acl}\left(B \vec{a}_{1}\right), \vec{a}_{3} \in \operatorname{acl}\left(B \vec{a}_{1} \vec{a}_{2}\right)$. Note that $\vec{a}_{2} \in \operatorname{acl}\left(\vec{a}_{1} B h\right)$, so $\vec{a} h \downarrow_{e} B$ implies that $\vec{a}_{2} \in \operatorname{acl}\left(\vec{a}_{1} e h\right)$ and thus $H B(\vec{a} / B)=H B(\vec{a} / e)$. Since $\vec{a} h \downarrow_{e}^{e} B$, we also have $\vec{a}_{3} \in \operatorname{acl}\left(e \vec{a}_{1} \vec{a}_{2}\right)$. Since $H B(\vec{a} / B)=H B(\vec{a} / e)$ and $\vec{a} h \downarrow_{e} B$ by our characterization of forking in $T^{i n d}$ we get $\vec{a} \downarrow_{e}^{i n d} B$.

Proposition 5.13. Let $(M, H)$ be a sufficiently saturated $H$-structure of $T, B \subset M$ an $H$-independent set, and $\vec{a} \in M$. Then $C b_{H}(\vec{a} / B)$ and $\left.C b(\vec{a} H B(\vec{a} / B) / B)\right)$ are interalgebraic.

Proof. Let $e=C b(\vec{a} H B(\vec{a} / B) / B))$. We saw in the previous lemma that $\vec{a} \downarrow_{e}^{\text {ind }} B$ and thus $C b_{H}(\vec{a} / B) \in \operatorname{acl}^{e q}(e)$. Now let $\left\{\vec{a}_{i}: i<\omega\right\}$ be an $\mathcal{L}_{H}$-Morley sequence in $\operatorname{tp}_{H}\left(\vec{a} / \operatorname{acl}_{H}^{\text {eq }}(B)\right)$. Let $h_{j}=H B\left(\vec{a}_{j} / B\right)$ (viewed as an imaginary representing a finite set). Note that $h_{j} \in \operatorname{dcl}_{H}\left(\vec{a}_{j} B\right)$. Thus $\left\{\vec{a}_{i} h_{i}: i<\omega\right\}$ is also an $\mathcal{L}_{H}$-Morley sequence over $B$. This implies $h_{j}=H B\left(\vec{a}_{j} / B \vec{a}_{<j} h_{<j}\right)$, and hence $\operatorname{tp}\left(\vec{a}_{j} h_{j} / B \vec{a}_{<j} h_{<j}\right)$ does not fork (in the sense of $\mathcal{L}$ ) over $B$. Thus, $\left\{\vec{a}_{i} h_{i}: i<\omega\right\}$ is also an $\mathcal{L}$-Morley sequence over $B$ in $\operatorname{tp}(\vec{a} h / B)$. Since $\operatorname{tp}\left(\vec{a}_{0} h_{0} /\left\{\vec{a}_{i} h_{i}: 0<i<\omega\right\} B\right)$ is a free extension of $\operatorname{tp}\left(\vec{a}_{0} h_{0} /\left\{\vec{a}_{i} h_{i}: 0<i<\omega\right\}\right)$ we also get that $e=C b\left(\vec{a}_{0} h_{0} /\left\{\vec{a}_{i} h_{i}: 0<\right.\right.$ $i<\omega\})$. It follows that $e \in \operatorname{acl}^{e q}\left(\left\{\vec{a}_{i} h_{i}: i<\omega\right\}\right)$.

Since $T^{i n d}$ is supersimple there is $N \in \omega$ such that for all $n \geq N, \vec{a}_{n} \downarrow_{\vec{a}_{<N}}^{i n d} B$. In particular $H B\left(\vec{a}_{n} / B\right)=H B\left(\vec{a}_{n} / \vec{a}_{<N}\right)$ and thus $h_{n} \in \operatorname{dcl}_{H}\left(\vec{a}_{i}: i<\omega\right)$ for every $n$. We then get $e \in \operatorname{acl}_{H}^{e q}\left(\left\{\vec{a}_{i}: i<\omega\right\}\right)$. Now, since $\left\{\vec{a}_{i}: i<\omega\right\}$ is a Morley sequence in $\operatorname{tp}_{H}\left(\vec{a} / \operatorname{acl}_{H}^{e q}(B)\right)$, we have

$$
\left\{\vec{a}_{i}: i<\omega\right\} \underset{C b_{H}(\vec{a} / B)}{\stackrel{i n d}{\downarrow}} B,
$$

and thus also

$$
\left\{\vec{a}_{i}: i<\omega\right\} \underset{C b_{H}(\vec{a} / B)}{\stackrel{i n d}{\downarrow}} e .
$$

It follows that $e \in \operatorname{acl}_{H}^{e q}\left(C b_{H}(\vec{a} / B)\right)$, as needed.

Remark 5.14. Note that Proposition 5.13 implies geometric elimination of imaginaries in $T^{\text {ind }}$ down to imaginaries of $T$, when $T$ is a supersimple $S U-r a n k 1$ structure.

Question 5.15. If $T$ is a geometric theory, does $T^{i n d}$ have (geometric) elimination of imaginaries down to imaginaries of $T$ ?

Example 5.16. Let $(V,+, 0, H)=\left(V,+, 0,\left\{v_{i}: i \in \omega\right\}\right)$ be the structure from Example 5.4. We will give another proof of non-1-basedness of $T^{\text {ind }}=T h(V,+, 0, H)$, using Lemma 5.13. Take $t, u, v_{1}$ as in Example 5.4, so $u, t$ are generic and $t=u+v_{1}$.

First note that $H B(t / u)=\left\{v_{1}\right\}$. Now, by Lemma 5.13, $C b_{H}(t / u)$ is interalgebraic (in $\left(T^{i n d}\right)^{e q}$ ) with $C b\left(t v_{1} / u\right)$. Note that $C b\left(t v_{1} / u\right)$ is interdefinable with $u$. On the other hand, $u \notin \operatorname{acl}_{H}(t)=\operatorname{acl}(t)=\operatorname{span}(t)$. Thus, $C b_{H}(t / u)$ is not algebraic over $t$, and therefore $T^{i n d}$ is not 1-based.

Let $t^{\prime}=u+v_{2}$, then $t, t^{\prime}$ are the first two elements in a Morley sequence in $\operatorname{tp}_{H}(t / u)$. Note that $t-t^{\prime}=v_{1}-v_{2}$, so $v_{1}, v_{2} \in \operatorname{acl}_{H}\left(t, t^{\prime}\right)$ and thus $u \in \operatorname{acl}_{H}\left(t, t^{\prime}\right)$. We will show below that when $T$ is 1-based, $T^{\text {ind }}$ is 2 -based: we need two elements in a Morley sequence in $T^{i n d}$ to recover the canonical base.

Carmona [10] proved that when $T$ is linear $S U$-rank one theory, $T^{i n d}$ is CMtrivial. We will show below that if $T$ is 1-based, then $T^{\text {ind }}$ is 2-based:

Proposition 5.17. Let $T$ be a simple theory of $S U-r a n k 1$ and assume that $T$ is 1-based. Let $(M, H) \models T^{\text {ind }}$ be saturated, let $A \subset M$ be small and let $p \in S_{k}^{H}(A)$. Then whenever $\left\{\vec{a}^{i}: i \in \omega\right\}$ is an $\mathcal{L}_{H}$-Morley sequence in $p$ over $A$ we have that $\vec{a}^{2} \downarrow_{\vec{a}^{0} \vec{a}^{1}}^{\text {ind }} A$.

Proof. Let $\left\{\vec{a}^{i}: i \in \omega\right\}$ be an $\mathcal{L}_{H}$-Morley sequence in $p$ over $A$. We can write $\vec{a}^{i}=\vec{a}_{1}^{i} \vec{a}_{2}^{i} \vec{a}_{3}^{i}$ where $\vec{a}_{1}^{i}$ is an independent tuple over $A H(M), \vec{a}_{2}^{i}$ is an independent tuple over $A \vec{a}_{1}^{i}$ and $\vec{a}_{2}^{i} \in \operatorname{scl}\left(A \vec{a}_{1}^{i}\right)$ and $\vec{a}_{3}^{i} \in \operatorname{acl}\left(A \vec{a}_{1}^{i} a_{2}^{i}\right)$. Let $\vec{h}^{i}=H B\left(\vec{a}^{i} / A\right)$ seen as a tuple. We may choose the ordering of $\vec{h}^{i}$ so that $\left\{\vec{a}^{i} \vec{h}^{i}: i \in \omega\right\}$ is an $\mathcal{L}_{H}$-Morley sequence in $\operatorname{tp}\left(\vec{a}^{0} \vec{h}^{0} / A\right)$. Note that both $\left\{\vec{a}^{i}: i \in \omega\right\}$ and $\left\{\vec{a}^{i} \vec{h}^{i}: i \in \omega\right\}$ are $\mathcal{L}$ Morley sequences over $A$. Indeed, since $\vec{a}^{i} \vec{h}^{i} \downarrow_{A}^{\text {ind }} \vec{a}^{0} \vec{h}^{0} \ldots \vec{a}^{i-1} \vec{h}^{i-1}$, we have that $\vec{a}_{1}^{i} \vec{h}^{i}$ is an acl-independent tuple over $A \vec{a}^{0} \vec{h}^{0} \ldots \vec{a}^{i-1} \vec{h}^{i-1}$. Since $\vec{a}^{i} \vec{h}^{i} \in \operatorname{acl}\left(A \vec{a}_{1}^{i} \vec{h}^{i}\right)$, it follows that $\vec{a}^{i} \vec{h}^{i} \downarrow_{A} \vec{a}^{0} \vec{h}^{0} \ldots \vec{a}^{i-1} \vec{h}^{i-1}$, and thus, $\left\{\vec{a}^{i} \vec{h}^{i}: i \in \omega\right\}$ is an $\mathcal{L}$-Morley sequence over $A$. Then clearly $\left\{\vec{a}^{i}: i \in \omega\right\}$ is also $\mathcal{L}$-Morley over $A$.

Since $T$ is 1 -based and $\left\{\vec{a}^{i} \vec{h}^{i}: i \in \omega\right\}$ is an $\mathcal{L}$-Morley sequence, we have that $\vec{a}^{1} \vec{h}^{1} \downarrow_{\vec{a}^{0} \vec{h}^{0}} A$, in particular $\vec{a}_{2}^{1} \in \operatorname{acl}\left(\vec{a}_{1}^{1} \vec{h}^{1} \vec{a}_{1}^{0} \vec{a}_{2}^{0} \vec{h}^{0}\right)$. Since $T$ is 1-based and $\left\{\vec{a}^{i}: i \in\right.$ $\omega\}$ is a $\mathcal{L}$-Morley sequence, we also get $\vec{a}_{3}^{1} \in \operatorname{acl}\left(\vec{a}_{1}^{1} \vec{a}_{2}^{1} \vec{a}_{1}^{0} \vec{a}_{2}^{0} \vec{a}_{3}^{0}\right)$. Thus $H B\left(\vec{a}^{1} / \vec{a}^{0}\right) \subset$ $\left\{\vec{h}^{0} \vec{h}^{1}\right\}$. Similarly, $H B\left(\vec{a}^{2} / \vec{a}^{0}\right) \subset\left\{\vec{h}^{0} \vec{h}^{2}\right\}$ and $H B\left(\vec{a}^{2} / \vec{a}^{1}\right) \subset\left\{\vec{h}^{1} \vec{h}^{2}\right\}$.

Note that $\vec{h}_{2}=H B\left(\vec{a}^{2} / A\right)=H B\left(\vec{a}^{2} / A \vec{a}^{0} \vec{a}^{1}\right) \subset H B\left(\vec{a}^{2} / \vec{a}^{0} \vec{a}^{1}\right)$. We want to show that $\vec{a}^{2} \downarrow_{\vec{a}^{0} \vec{a}^{1}}^{\text {ind }} A$, so it suffices to show that $\vec{h}_{2}=H B\left(\vec{a}^{2} / \vec{a}^{0} \vec{a}^{1}\right)$ and to show this it suffices to prove that $H B\left(\vec{a}^{2} / \vec{a}^{0} \vec{a}^{1}\right) \subset \vec{h}_{2}$. Note that $H B\left(\vec{a}^{2} / \vec{a}^{0} \vec{a}^{1}\right) \subset H B\left(\vec{a}^{2} / a^{0}\right) \cap$ $H B\left(\vec{a}^{2} / \vec{a}^{1}\right)=\left\{\vec{h}^{0} \vec{h}^{2}\right\} \cap\left\{\vec{h}^{1} \vec{h}^{2}\right\}$. Since $\vec{h}^{i}=H B\left(\vec{a}^{i} / A\right)$ are disjoint from $\operatorname{acl}(A)$, and $\left\{\vec{a}^{i} \vec{h}^{i}: i \in \omega\right\}$ is an $\mathcal{L}$-Morley sequence, the tuples $\vec{h}^{i}$ are disjoint. Thus, $\left\{\vec{h}^{0} \vec{h}^{2}\right\} \cap\left\{\vec{h}^{1} \vec{h}^{2}\right\}=\vec{h}^{2}$. Hence $H B\left(\vec{a}^{2} / \vec{a}^{0} \vec{a}^{1}\right) \subset \vec{h}_{2}$, as needed.

Remark 5.18. Note that a 2-based SU-rank 1 theory is 4-pseudolinear, meaning that canonical bases of plane curves have $S U-r a n k \leq 4$. Indeed, suppose $S U(a b / A)=$ 1, and let $\left\{a_{i} b_{i}: i \in \omega\right\}$ be a Morley sequence in $\operatorname{tp}(a b / A)$. Then 2-basedness implies $C b(a b / A) \subset \operatorname{acl}^{e q}\left(a_{0} b_{0}, a_{1} b_{1}\right)$, and therefore $S U(C b(a b / A)) \leq 4$. In [9], it is shown that pseudolinear strongly minimal theories are locally modular (1-based). In [26], it is shown that a pseudolinear $\omega$-categorical SU-rank 1 theory is 1-based. In [19], Hrushovski gives an example of an $\omega$-categorical SU-rank 1 theory which is not 1based. By the above, this theory is not 2-based (or even finitely based), but it is known to be CM-trivial. Thus, CM-triviality does not imply 2-basedness.
5.3. Thorn rank one. Assume that $T$ is a thorn rank one theory. The goal of this subsection is to show that $T^{i n d}$ is super-rosy of thorn-rank $\leq \omega$. Our proof follows the proof of super-rosyness given by Boxall for lovely pairs of thorn rank one theories.

Theorem 5.19. The theory $T^{i n d}$ is super-rosy of thorn rank less that or equal to $\omega$.

Proof. Let $(M, H) \models T^{i n d}$ be highly saturated. In order to show that $T^{i n d}$ is super-rosy, we need to understand two steps:

Claim 1 Let $\varphi(x, \vec{c})$ define an infinite subset of $H(M)$. Then $\varphi(x, \vec{c})$ does not thorn divide over $\emptyset$.

The proof is word by word the same one as the one presented in [6].
Claim 2 Let $\theta(x, \vec{a})$ be an $\mathcal{L}_{H}$ formula defining a large subset of $M$. Then $\theta(x, \vec{a})$ does not thorn divide over $\emptyset$.

The proof is again very similar to the one presented by Boxall in [6] for lovely pairs of thorn rank one theories, but we will do some small changes to see how the arguments adapt to the new setting.

Suppose $\theta(x, \vec{a})$ thorn divides. Let $\hat{a}$ be the canonical parameter of $\theta(x, \vec{a})$, we will also write the definable set as $\theta(x, \hat{a})$. Let $D$ be a finite set such that $\hat{a} \notin \operatorname{acl}_{H}^{e q}(D)$ and such that $\left\{\theta\left(x, \hat{a}^{\prime}\right): \hat{a}^{\prime} \models \operatorname{tp}(\hat{a} / D)\right\}$ is $k$-inconsistent. We may assume that $D \subset M$, that is, it contains only real elements. By noticing that $H B(D) \in \operatorname{acl}_{H}(D)$ and exchanging $D$ for $D \cup H B(D)$ we may also assume that $D$ is $H$-independent.

Let $b \in \theta(x, \hat{a})$, since the family $\left\{\theta\left(x, \hat{a}^{\prime}\right): \hat{a}^{\prime} \models \operatorname{tp}(\hat{a} / D)\right\}$ is $k$-inconsistent, there are at most $k-1$ conjugates of $\hat{a}$ over $b D$, so $\hat{a} \in \operatorname{acl}_{H}(b D)$. Since $\theta(x, \hat{a})$ defines an infinite large set, we may assume that $b \notin \operatorname{scl}_{H}(\hat{a} D)$. Let $\varphi(\hat{y}, x)$ be an algebraic formula in the variable $\hat{y}$ such that $(M, H) \models \varphi(\hat{a}, b)$. Let $\hat{a}^{*}$ be the canonical parameter of $\varphi(\hat{a}, x)$. Note that $\hat{a}^{*} \in \operatorname{dcl}(\hat{a})$.

Claim $3 \hat{a} \in \operatorname{acl}\left(\hat{a}^{*} D\right)$.
Let $n$ be the multiplicity of $\varphi(\hat{y}, x)$ (in the variable $\hat{y}$ ). Let $\hat{a}_{1}, \ldots, \hat{a}_{n+1}$ be realizations of $\operatorname{tp}\left(\hat{a} / \hat{a}^{*} D\right)$. Then for any $b^{\prime}$ with $\varphi\left(\hat{a}^{*}, b^{\prime}\right)$, we also have $\varphi\left(\hat{a}_{1}, b^{\prime}\right), \ldots, \varphi\left(\hat{a}_{n+1}, b^{\prime}\right)$ and thus there are $i<j \leq n+1$ such that $\hat{a}_{i}=\hat{a}_{j}$.

Thus, $\hat{a}, \hat{a}^{*}$ be interalgebraic over $D$. By Proposition 3.12 there is an $\mathcal{L}$-definable set $\psi(x, \vec{c})$, where $\vec{c}$ is a real tuple, such that $\psi(x, \vec{c}) \triangle \varphi\left(\hat{a}^{*}, x\right)$ is small, where $\triangle$ is a boolean connective for the symmetric difference. Note that we can choose $\vec{c}$ to be a real base of $\hat{a}^{*}$.

Let $E(\vec{u}, \vec{v})$ be the equivalence relation $\psi(x, \vec{u}) \triangle \psi(x, \vec{v})$ is finite. Since $T$ eliminates $\exists^{\infty}, E(\vec{z}, \vec{w})$ is a definable equivalence relation. Let $e=\vec{c} / E$.

Let $\psi\left(x, \vec{c}^{\prime}\right)$ be such that $\psi\left(x, \vec{c}^{\prime}\right) \triangle \psi(x, \vec{c})$ is small. It is were infinite, since $\psi\left(x, \vec{c}^{\prime}\right) \triangle \psi(x, \vec{c})$ is an $\mathcal{L}$ definable set it would be large. Thus if $\psi\left(x, \vec{c}^{\prime}\right) \Delta \psi(x, \vec{c})$ is small, then $\psi\left(x, \vec{c}^{\prime}\right) \triangle \psi(x, \vec{c})$ is finite and $E\left(\vec{c}, \vec{c}^{\prime}\right)$. Thus $e=\vec{c} / E \in \operatorname{acl}_{H}(\hat{a} D)$.

Claim $4 \hat{a} \in \operatorname{acl}(e D)$.
Recall that $n$ is the multiplicity of $\varphi(\hat{y}, x)$ (in the variable $\hat{y}$ ). Let $\hat{a}_{1}, \ldots, \hat{a}_{n+1}$ be realizations of $\operatorname{tp}(\hat{a} / e D)$. Then there are $c_{1}, \ldots, c_{n+1}$ such that $\psi\left(x, c_{i}\right) \Delta \varphi\left(\hat{a}_{i}, x\right)$ is small for $i \leq n+1$. Since $e=c_{i} / E$ for $i \leq n+1$, we have that $\psi\left(x, c_{i}\right) \Delta \psi\left(x, c_{i}\right)$ is finite for $i \leq n+1$. Let $b^{\prime \prime} \in \bigwedge_{i \leq n+1} \psi\left(x, c_{i}\right) \wedge \bigwedge_{i \leq n+1} \varphi\left(\hat{a}_{i}, x\right)$. Then we have $\varphi\left(\hat{a}_{1}, b^{\prime \prime}\right), \ldots, \varphi\left(\hat{a}_{n+1}, b^{\prime \prime}\right)$ and thus there are $i<j \leq n+1$ such that $\hat{a}_{i}=\hat{a}_{j}$.

Thus $e$ and $\hat{a}$ are interalgebraic over $D$. Note that $e \in \operatorname{acl}_{H}(b D) \backslash \operatorname{acl}_{H}(D)$. Since $b \notin \operatorname{scl}(D)$ the set $b D$ is $H$-independent and thus $e \in \operatorname{acl}(b D) \backslash \operatorname{acl}(D)$, but $b \notin \operatorname{acl}(e D)$, a contradiction since $T$ has thorn rank one.

As with the supersimple case, when $T$ is trivial, the thorn rank of $T^{i n d}$ is one and when $T$ is not trivial, the thorn rank of $T^{i n d}$ is $\omega$. The proof follows easily from the previous theorem and we leave the details to the reader.

Question 5.20. In [4] the authors developed a theory of weakly one-based geometric theories. A generalization of this notion appears in [7] in the setting of structures with a robust independence notion (for example rosy theories), where it is proved that when $T$ is rosy of thorn rank one, weakly one-basedness coincides with linearity.

Find a reasonable notion of weak 2-basedness in the setting of rosy theories and explore its properties, in particular does Proposition 5.17 hold in this setting?
5.4. NIP theories. We finish this section by addressing the question of preservation of NIP.

Proposition 5.21. Let $T$ be a geometric theory, $(M, H)$ a sufficiently saturated $H$-structure of $T$, and suppose $T$ has NIP. Then $T h(M, H)$ also has NIP.
Proof. We apply the criterion from [12, Thm 2.4]. We begin by showing that every formula $\phi(\vec{x}, \vec{y})$ has NIP over $H(\vec{x})$. Assume otherwise, so there is an $\mathcal{L}_{H}$-formula $\phi(\vec{x}, \vec{y}), I=\left(\vec{b}_{i}: i \in \omega\right)$ an indiscernible sequence of elements in $H(M)$ and $\vec{a} \in M$ such that $\phi\left(\vec{b}_{i}, \vec{a}\right)$ holds iff $i$ is even. Then by Proposition 3.5 we have that there is an $\mathcal{L}$-formula $\psi(\vec{x}, \vec{z})$ and an element $\vec{d}$ such that $\psi(\vec{x}, \vec{d}) \wedge H(\vec{x})$ holds if and only if $\phi(\vec{x}, \vec{a}) \wedge H(\vec{x})$ holds. Thus the $\mathcal{L}$-formula $\psi(\vec{x}, \vec{y})$ has the IP, a contradiction. By Proposition 3.2 every formula in $(M, H)$ is equivalent to a boolean combination of existential formulas over $H$. This fact together with Theorem 2.4 [12] shows that $T h(M, H)$ also has NIP.

Remark 5.22. The above result could also have been proved doing very small modifications on Theorem 2.8 [5]. Also, Theorem 2.11 [5] can be easily modified to show that if $T$ is strongly dependent then $T h(M, H)$ is strongly dependent.

Now we will study the special case when $T$ is geometric and has finite dp-rank
Proposition 5.23. Let $T$ be a geometric theory of $d p-r a n k ~ k<\omega$ and let ( $M, H$ ) be a sufficiently saturated $H$-structure of $T$. If $T$ is trivial and $\mathrm{dcl}=\mathrm{acl}$, then $T h(M, H)$ has dp-rank $k$.

Proof. Since $T$ is trivial, every formula $\psi(x, \vec{y})$ in $T^{i n d}$ is a boolean combination of $\mathcal{L}$-formulas and formulas of the form $H(f(x, \vec{y}))$ where $f(x, \vec{y})$ is an $\mathcal{L}$-definable function over $\emptyset$.

Claim Let $\left(\vec{a}_{i}: i \in \omega\right)$ be an $\mathcal{L}_{H}$-indiscernible sequence and let $b \in M$ and let $f(x, \vec{y})$ be an definable function over $\emptyset$ in the language $\mathcal{L}$. Then for all $i \in \omega$ either $H\left(f\left(b, \vec{a}_{i}\right)\right)$ or $\neg H\left(f\left(b, \vec{a}_{i}\right)\right)$.

Since $T$ is trivial and $f(x, \vec{y})$ is an $\mathcal{L}$-definable function, either there is an $\mathcal{L}$ definable function $h(x)$ such that for all $i t\left(x, \vec{a}_{i}\right)=h(x)$ or there is $\mathcal{L}$-definable function $g(\vec{y})$ such that for all $i t\left(x, \vec{a}_{i}\right)=g\left(\vec{a}_{i}\right)$. The existence of $h$ or $g$ only depends on the type of $\vec{a}_{i}$. If $t\left(x, \vec{a}_{i}\right)=g\left(\vec{a}_{i}\right)$ then since $\left(\vec{a}_{i}: i \in \omega\right)$ is $\mathcal{L}_{H^{-}}$ indiscernible we have that the value of $H\left(f\left(b, \vec{a}_{i}\right)\right)$ agrees with the value of $H\left(g\left(\vec{a}_{0}\right)\right)$. If $t\left(x, \vec{a}_{i}\right)=h(x)$ then the value of $H\left(f\left(b, \vec{a}_{i}\right)\right)$ agrees with the value of $H(h(b))$. In any case, the value of $H\left(f\left(b, \vec{a}_{i}\right)\right)$ does not depend on $i$.

Assume there is an ICT pattern of depth $n$ in $(M, H)$. Then there are $\mathcal{L}_{H}$ formulas $\psi_{1}\left(x, \vec{y}_{1}\right), \ldots, \psi_{n}\left(x, \vec{y}_{n}\right)$ and there are $\mathcal{L}_{H}$-indiscernible sequences sequences $\left\{\left(\vec{a}_{i}^{j}: i<\omega\right): j \leq n\right\}$ that form a ICT pattern of depth $n$. Let $i_{1}, i_{2}, \ldots, i_{n}<\omega$ and let $b$ realize $\psi_{1}\left(x, \vec{a}_{1}^{i_{1}}\right) \wedge \psi_{2}\left(x, \vec{a}_{2}^{i_{2}}\right) \wedge \cdots \wedge \psi_{n}\left(x, \vec{a}_{n}^{i_{n}}\right)$ and the negation of all other formulas. Each formula $\psi_{1}\left(x, \vec{y}_{1}\right)$ is a boolean combination of $\mathcal{L}$-formulas and formulas of the form $H\left(f\left(x, \vec{y}_{1}\right)\right)$ where $f\left(x, \vec{y}_{1}\right)$ is an $\mathcal{L}$-definable function. Since the value of $H\left(f\left(b, \vec{a}_{1}^{i}\right)\right)$ does not depend on $i$ we may replace each $\psi_{i}\left(x, \vec{y}_{1}\right)$ just by the $\mathcal{L}$-formulas inside it and obtain an ICT pattern of depth $n$ in $(M, H)$.
Question 5.24. Does the result of the previous Proposition remain true if we remove the assumption $\mathrm{acl}=\mathrm{dcl}$ ?

Proposition 5.25. Let $T$ be a geometric theory of dp-rank $k<\omega$. Then $T^{\text {ind }}$ has dp-rank greater than $n$ for every $n \in \mathbb{N}$ but bounded by $\aleph_{0}$.
Proof. Since $T^{i n d}$ is strongly dependent, then the dp-rank is bounded by $\aleph_{0}$. Let $(M, H)$ be a sufficiently saturated $H$-structure. Let $a_{1}, \ldots, a_{n}, a_{n+1} \in M$ be an algebraic $n+1$-gon. We may assume that $a_{1}, \ldots, a_{n} \in H(M)$, thus $H B\left(a_{n+1}\right)=$ $\left\{a_{1}, \ldots, a_{n}\right\}$ and $a_{1}, \ldots, a_{n} \in \operatorname{acl}\left(a_{n+1}\right)$. Since $d p-r k\left(H\left(x_{1}\right) \wedge \cdots \wedge H\left(x_{n}\right)\right) \geq n$, we have dp-rank $(x=x) \geq n$.

Remark 5.26. Let $T$ be a geometric theory which is dp-minimal and let $(M, H)$ be a sufficiently saturated $H$-structure of $T$. Let $C \subset M$ and let $\vec{a} \in M^{n}$ be such that $\vec{a} \in \operatorname{scl}(C)$. Let $\vec{h}=H B(\vec{a} / C)$. Then $\vec{a}$ is interalgebraic with $\vec{h}$ over $C$. Each $d \in \vec{h}$ has a type of dp-rank one over $C$, so small tuples can be coordinatized in terms of dp-rank one types. In the stable setting, for $a \notin \operatorname{scl}(C)$ we had that $\operatorname{tp}(a / C)$ was regular. What is the corresponding notion in the setting of strongly dependent theories? Does it have burden one?

## 6. Groups

In this section we study the special case where $M$ is rosy. As before we consider the $H$-structure $(M, H)$ and our aim in this section is to study definable groups in $(M, H)$. We will show that there are no small definable groups. Then we consider the special case where $M=G$ is a group with $R M(G)=1$. We will show that the $\mathcal{L}_{H}$-definable subgroups of $G^{n}$ are $\mathcal{L}$-definable. Finally we show that if $M$ is stable of $U$-rank one, the connected component of any $\mathcal{L}_{H}$-definable group is isomorphic to an $\mathcal{L}$-type definable group.

We will use the following tool in the rosy setting:
Fact 6.1. Let $T$ be rosy, let $M \models T$ and let $G \subset M^{n}$ be a definable group. Then $G$ has generics in the sense that there is $g \in G$ such that for $h \in G$ with $g \downarrow h$ we have $g h \downarrow h$.

We start by showing that the generic elements in definable groups are independent from $H$ :

Proposition 6.2. Let $M$ be a model of a thorn rank one theory and assume that $(M, H)$ is a $\aleph_{0}$-saturated $H$-structure. Let $A \subset M$ be finite and let $T \leq M^{n}$ be a $\mathcal{L}_{H}$-definable group over $A$. Let $\vec{b} \in T$ be a generic element of the group, then $H B(\vec{b} / A)=\emptyset$.

Proof. We may assume that $A=A \cup H B(A)$ and thus that $A$ is $H$-independent. Let $\vec{b}, \vec{c} \in T$ be independent generics (over $A$ ) and let $\vec{b} \cdot \vec{c}$ stand for the product of $\vec{b}, \vec{c}$ in the group $T$. Since $\vec{c} \downarrow_{A}^{H} \vec{b}, H B(\vec{c} / A)=H B(\vec{c} / A \vec{b})$ and $H B(\vec{c} \vec{b} / A)=$ $H B(\vec{c} / A) \cup H B(\vec{b} / A)$ and thus $H B(\vec{c} \cdot \vec{b} / A) \subset H B(\vec{c} / A) \cup H B(\vec{b} / A)$.

Since $\vec{b}, \vec{c}$ are independent generics, $\vec{b} \cdot \vec{c} \downarrow_{A}^{H} \vec{b}$ and thus $H B(\vec{b} \cdot \vec{c} / A) \downarrow_{A}^{H} H B(\vec{b} / A)$ and so $H B(\vec{b} \cdot \vec{c} / A) \cap H B(\vec{b} / A)=\emptyset$. Similarly one has $H B(\vec{b} \cdot \vec{c} / A) \cap H B(\vec{c} / A)=\emptyset$. This together with $H B(\vec{c} \cdot \vec{b} / A) \subset H B(\vec{c} / A) \cup H B(\vec{b} / A)$ proves that $H B(\vec{c} \cdot \vec{b} / A)=\emptyset$. Since $\vec{c} \cdot \vec{b}$ is generic, and $\vec{c}^{-1}$ is also generic and independent from $\vec{c} \cdot \vec{b}$ over $A$, we get that $H B(\vec{b} / A)=H B\left(\vec{b} \cdot \vec{c} \cdot \vec{c}^{-1} / A\right)=\emptyset$.

Corollary 6.3. Let $M$ be a model of a thorn rank one theory and assume that $(M, H)$ is a $\aleph_{0}$-saturated $H$-structure. Let $A \subset M$ be finite and let $T \leq M^{n}$ be a $\mathcal{L}_{H^{-}}$-definable group over $A$ and assume that $T$ is small. Then $T$ is finite.

We will now consider two settings, first the stable one and then topological one. Our goal is to see how close are $\mathcal{L}_{H}$-definable groups from being $\mathcal{L}$-definable.

### 6.1. Stable groups.

Notation 6.4. Let $M$ be a structure of Morley rank one and assume that ( $M, H$ ) is an $H$-structure. For an $\mathcal{L}$-formula $\psi$, we denote by $R M(\psi)$ the Morley rank and $d M(\psi)$ the Morley degree calculated within Th(M). Similarly, for an $\mathcal{L}_{H}$-formula $\psi$ we denote by $R M_{H}(\psi), d M_{H}(\psi)$ the Morley rank and the Morley degree inside the theory $\operatorname{Th}(M, H)$.

Assume now that $M$ is a group. For a complete $\mathcal{L}$-type p, we denote by $\operatorname{Stab}(p)$ the stabilizer of $p$ in the language $\mathcal{L}$ and for a complete $\mathcal{L}_{H}$-type $q$ we write $\operatorname{Stab}_{H}(p)$ for its stabilizer.
Proposition 6.5. Let $G$ be group with $R M(G)=1$ and assume that $(G, H)$ is a $\aleph_{0}$-saturated $H$-structure. Let $A \subset G$ be finite and let $T \leq G^{n}$ be a $\mathcal{L}_{H}$-definable subgroup over $A$. Then $T$ is $\mathcal{L}$-definable.
Proof. Let $A$ and $T$ be as above. By exchanging $A$ for $A \cup H B(A)$ we may assume that $A$ is $H$-independent. Let $\vec{b} \in T$ be generic, so $H B(\vec{b} / A)=\emptyset$.

Assume first that $T=T^{0}$, that is, $T$ is connected. Since $H B(\vec{b} / A)=\emptyset$, we may assume that we can write $\vec{b}=\left(b_{1}, \ldots, b_{l}, b_{l+1}, \ldots, b_{n}\right)$, where $\left(b_{1}, \ldots, b_{l}\right)$ are $H$-independent and $b_{l+1}, \ldots, b_{n} \in \operatorname{acl}\left(b_{1}, \ldots, b_{l}\right)$. Let $p=\operatorname{tp}_{H}(\vec{b} / A)$ and note that $R M_{H}(\vec{b} / A)=\omega l$. Since $\vec{b}$ is generic, $\operatorname{Stab}_{H}(p)=T$. Let $q=\operatorname{tp}(\vec{b} / A)$, so $q$ is the restriction of $p$ to the old language.

Claim Let $\vec{c} \models q$ be such that $\vec{b} \downarrow_{A} \vec{c}$, then $\vec{b} \cdot \vec{c} \models q$.
We may assume that $\vec{b}, \vec{c} \downarrow_{A} H$, so $\vec{b}, \vec{c} \models p$ and $\vec{b} \downarrow_{A}^{H} \vec{c}$. Since $p$ is the unique generic type of $T$, we must have that $\vec{b} \cdot \vec{c} \models p$ and thus $\vec{b} \cdot \vec{c} \models q$ as we wanted.

Let $D=\operatorname{Stab}(q)$, where we now take the stabilizer in the $\mathcal{L}$ language. Since $q$ is closed under generic multiplication and inverses, every member of $D$ is a product of two realizations of $q$, we have that $D=q \cdot q$. Since $q$ is a generic for $D$, we obtain then that $R M(D)=l, d M(D)=1, R M_{H}(D)=\omega l, d M_{H}(D)=1$. Also $p \cdot p \subset q \cdot q=D$, so $T=p \cdot p \leq D$. Since $M R_{H}(T)=\omega l$ and $d M_{H}(D)=1$ we must have that $D=T$.

Now assume that $T$ is not necessarily connected. Then $T=T^{0} \cup \vec{b}_{1} T^{0} \cup \cdots \cup \vec{b}_{k} T^{0}$ for some finite $\vec{b}_{1}, \ldots, \vec{b}_{k} \in T$. Since $T^{0}$ is $\mathcal{L}$-definable so is $T$.

Proposition 6.6. Let $M$ be a stable structure of $U$-rank one and let $H$ be a subset of $M$ such that $(M, H)$ is a $\aleph_{1}$-saturated $H$-structure. Let $A \subset M$ be countable and let $T \subset M^{n}$ be a $\mathcal{L}_{H}$-definable group over $A$. Let $T^{0}$ be the connected component of $T$. Then $T^{0}$ is definably isomorphic to an $\mathcal{L}$-definable group.

Proof. We may assume by enlarging $A$ that $(A, H \cap A) \preceq(M, H)$ and that $(M, H)$ is saturated and strongly homogeneous over $A$. Thus every complete $\mathcal{L}$-type and every complete $\mathcal{L}_{H}$-type over $A$ is stationary. Also note that $T^{0}$ is $A$-definable. Let $b_{1}, b_{2}, a_{2}$ be independent generics in $T^{0}$. Let $a_{3}=b_{1} \cdot a_{2}$, let $a_{1}=b_{2}^{-1} \cdot a_{3}$, $b_{3}=b_{2} \cdot b_{1}^{-1}$. Note that since $b_{1}$ and $a_{2}$ are independent generics, $H B\left(b_{1}, a_{2} / A\right)=\emptyset$
and thus by Lemma $2.8 a_{3} \in \operatorname{acl}\left(b_{1}, a_{2}, A\right)$. To simplify the argument we will assume that $a_{3} \in \operatorname{dcl}\left(b_{1}, a_{2}, A\right)$. Similarly $a_{1} \in \operatorname{dcl}\left(b_{2}, a_{3}, A\right), b_{3} \in \operatorname{dcl}\left(b_{1}, b_{2}, A\right)$. Then $\left\{a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right\}$ forms an algebraic quadrangle in the language $\mathcal{L}$. Applying the group configuration construction to $\left\{a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right\}$ (see for example [8, 23]) we obtain a connected $\mathcal{L}$-type-definable group $G$. We will now follow the proof in [8] to understand how $G$ is related to $T^{0}$. Let $p=\operatorname{tp}\left(b_{2} / A\right)$, note that $p=\operatorname{tp}\left(a_{1} / A\right)$, and that $b_{2}$ defines a unique germ given by $h_{b_{2}}(x)=b_{2} \cdot x$, and this $\mathcal{L}$-function is defined for elements satisfying $p$ that are independent from $b_{2}$. The group $G$ is given by $p \times p / E$, where for $d_{1}, d_{2} \in p, c_{1}, c_{2} \in p,\left(d_{1}, d_{2}\right) E\left(c_{1}, c_{2}\right)$ if for $a \models p$ independent from $\left\{d_{1}, d_{2}, c_{1}, c_{2}\right\}, d_{1} \cdot\left(d_{2} \cdot a\right)=c_{1} \cdot\left(c_{2} \cdot a\right)$. In few words, every element in $G$ is formed as the product of two generics (realizations of $p$ ) and we identify the product $d_{1} \cdot d_{2}$ with $c_{1} \cdot c_{2}$ if they agree generically. We will now build a definable isomorphism between $T^{0}$ and $G$. For $t \in T^{0}$, let $b \models p$ be independent from $t$ and define $\varphi(t)=\left(b^{-1}, b \cdot t\right) / E$. Note that $\varphi$ is $A$-definable and does not depend on the choice of $b$.

Claim The map $\varphi$ is $1-1$.
Let $t_{1}, t_{2} \in T$ and let $b \models p$ be independent from $t_{1}, t_{2}$. If $\left(b^{-1}, b \cdot t_{1}\right) E\left(b^{-1}, b \cdot t_{2}\right)$ then for $a \models p$ generic, $b^{-1} \cdot b \cdot t_{1} \cdot a=b^{-1} \cdot b \cdot t_{2} \cdot a$ and thus $t_{1}=t_{2}$.

Claim The map $\varphi$ is onto.
Let $d_{1}, d_{2} \models p$ be generics. Let $a \models p$ be generic such that $a \downarrow_{A} H d_{1} d_{2}$. Note that by stationarity $a$ realizes the unique extension of $p$ which is $H$-independent and thus $a$ is a generic of the group $T^{0}$. Again by stationarity, $d_{1} \cdot a$ is generic in $T^{0}$, $a^{-1} \cdot d_{2}$ is also generic in $T^{0}$ and $\left(d_{1}, d_{2}\right) E\left(d_{1} \cdot a, a^{-1} \cdot d_{2}\right)$. Thus $t=\left(d_{1} \cdot a\right) \cdot\left(a^{-1} \cdot d_{2}\right)$ being a product of generics in $T^{0}$ belongs to $T^{0}$ and $\varphi(t)=\left(d_{1}, d_{2}\right) / E$.

It is easy to see that $\varphi$ is a homomorphism of groups and thus $\varphi$ is an isomorphism between $T^{0}$ and $G$.

Remark 6.7. Let $(M, H), T$ and $A$ be as in the previous proposition. Note that the connected component $T^{0}$ of $T$ is isomorphic to an $\mathcal{L}$-definable group and thus $T$ is $\mathcal{L}$-definable-by-bounded. In the case where $M$ is $\omega$-stable, the index of $T^{0}$ in $T$ is finite and thus $T$ is $\mathcal{L}$-definable-by-finite. In the later case, $T$ can be written as a semidirect product of $T^{0}$ and $T / T^{0}$, but the action of $T^{0}$ is $\mathcal{L}_{H}$-definable and it is not clear we can recover a $\mathcal{L}$-definable copy of $T$.

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